## PANDAA:

# Physical Arrangement Detection of Networked Devices through Ambient-Sound Awareness 

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## The Problem







## "Smart Offices"



## Meetings - Intuitive Content Sharing



## Requirements

- Must be accurate (sub-meter).
- Work on off-the-shelf devices, minimal requirement of specialized hardware.
- Non-intrusive, automated operation and maintenance.


## Related Work (Indoor Localization)

|  | Desired <br> Sub-meter <br> Accuracy | Requirement of <br> Specialized <br> Hardware | Non-intrusive |
| :---: | :---: | :---: | :---: |
| WiFi signal strength range/ <br> fingerprint |  | Low |  |
| Ultrasound-RF |  | High |  |
| Audible chirp ranging |  | Low |  |
| Ambient sound ranging <br> (PANDAA) |  | Low |  |



Problem Related work Proposed approach Evaluation Discussion

## PANDAA

## A microphone

Wireless connection
(t)

## PANDAA

## PANDAA

## PANDAA



Indoor ambient sounds:

- a door closing
- a barking dog
- human talk
- coughs
- hand claps
- a ringing phone
- finger snaps


## PANDAA



## Ambient Sound Processing Pipeline



## Get Pairwise Distances Using TDoA



Time difference of sound arrivals (TDoA) can be expressed as


## Estimate Distances Between Devices


unknown value
estimated value
Given one source $S$, we have one lower bound of $d_{A B}$

$$
\frac{\left|d_{S B}-d_{S A}\right| \leq d_{A B}}{\hat{\jmath}}
$$


a lower bound of $d_{A B}$

## Successive Estimation of $d_{A B}$



Given multiple sources, we have overlapped bounds of $d_{A B}$


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( $\rightarrow$ Electrical \& Computer

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## Successive Estimation of $d_{A B}$



Given multiple sources, we have overlapped bounds of $d_{A B}$


The maximal lower bound will get closer and closer to the actual $d_{A B}$. ( $\rightarrow$ Electrical \& Computer

## A Problem!

## Different Sound Source Locations



## Compensate for Pairwise Errors



Only two devices A, B
$S$ is not good for estimating the distance between
$A$ and $B$

- As \#devices increases, estimation accuracy can be improved
- A sound source may be bad for one particular device pair, but good for others.


## Compensate for Pairwise Errors



Only two devices A, B
$S$ is not good for estimating the distance between $A$ and $B$


If we have 2 more devices in the network
$S$ is not good for estimating the distance between $A$ -
$B$, but is good for $A-C, B-C$, and C-D

- As \#devices increases, estimation accuracy can be improved
- A sound source may be bad for one particular device pair, but good for others.


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## Meeting-room Experiments


photo

sensor nodes

- $8 \times 6 \mathrm{~m}^{2}$ meeting room
- Eight nodes (orange dots on the floor plan)
- IOO locations to generate ambient sound (grid intersections)
( $\rightarrow$ Electrical \& Computer


## Ambient Sound Used In Experiments

95 -second audio at each source location (the "grid") using loudspeaker

| Types | Durations (s) | Notes |
| :--- | :--- | :--- |
| Cough | 32 | 12 coughs from 6 individuals (2 males <br> and 4 females) |
| Conversation | 21 | Between a male and a female |
| Music \#1 | 21 | "Billie Jean" |
| Music \#2 | 21 | "The Sound of Silence" |

## Impulsive Sound Event Detection






- Averagely I event/cough; for other types, I event/sec.
- Effective to extract impulsive sound from all four sound types.
- Detection rate is high to generate sufficient events for arrangement detection.


## Estimated Locations vs. Ground-truths

\#Source: 1 Error:1.1789m

x: Sound sources $\boldsymbol{+}$ : Ground truths $\diamond$ : Estimated locations

## Estimated Locations vs. Ground-truths

\#Source: 2 Error: 1.041 m

x: Sound sources + : Ground truths $\diamond$ : Estimated locations

## Estimated Locations vs. Ground-truths



## Location Errors vs. \#Sound Sources



## Conclusions

- Novel approach - prove that using ambient sound in physical arrangement detection is possible.
- PANDAA achieves 0.17 m accuracy in the meetingroom experiments given uniformly distributed sound sources.

