

Construction of a signal model :

(time, space, GNN)

- (1) Introduce time/space marks t_n , abstract shift operator g and its operation on t_n ;
- (2) Extend to linear combinations of marks \rightarrow signal module ;
extend to linear combinations of shifts \rightarrow filter algebra .

What is the mathematical nature of step (1) ?

Discrete Markov Chain

System S of mutually exclusive states $t_n, n \in I \subseteq \mathbb{Z}^+$.

At time k ($k \in \mathbb{N}_0$) the uncertainty of the state is a random variable X_k . Its distribution is $(a_{k,n})_{n \in I}$, where $a_{k,n} = \text{prob}(X_k = t_n)$.

The transition probability $p_{m,n}^k = \text{prob}(X_{k+1} = t_m | X_k = t_n)$.

The transition probability matrix $Q^k = [p_{m,n}^k]_{m,n \in I}$. $(a_{k+1,n}) = (a_{k,n})Q^k$

Definition : Given initial distribution $(a_{0,n})$ of X_0

and $Q^k, k \in \mathbb{N}_0$, the sequence $X_0, X_1, \dots, X_k, \dots$ is called a Markov chain with discrete state space and of discrete time.

If $p_{m,n}^k = p_{m,n}^l$ for any $k, l \in \mathbb{N}_0$, then the chain has stationary transition probabilities, and it is homogeneous. Then $Q_{k+1}^k = Q$ for all k .

Q^k (or simply Q) is stochastic, i.e. all entries are non-negative, all column sums are equal to 1, no row consists only of zeros.

If $|I|$ is finite, the chain is finite.

Relation to signal models

| signal model | discrete Markov chains |
|------------------------|---|
| time/space marks t_n | states z_n |
| matrix $\varphi(z)$ | probability transition matrix \mathcal{Q} |

Examples:

(a) Infinite discrete time:

$$\begin{pmatrix} \ddots & 0 & & \\ & \ddots & 0 & \\ & & 1 & \\ & & & \ddots \end{pmatrix}$$

(b) Infinite space:

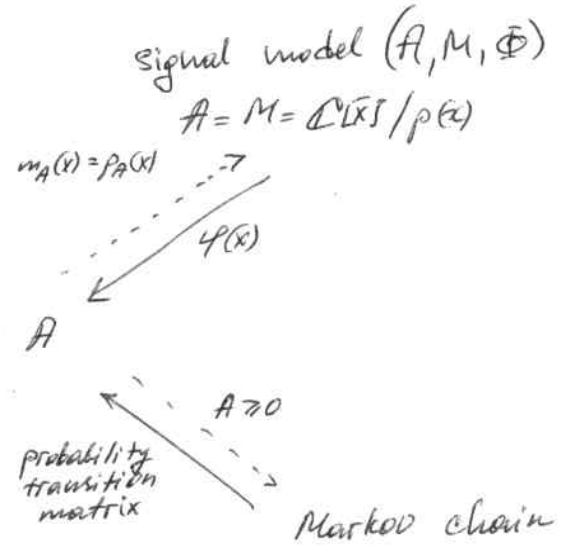
$$\begin{pmatrix} \ddots & & & & \\ & 1/2 & 0 & 1/2 & \\ & 1/2 & 0 & 1/2 & \\ & & 1/2 & 0 & 1/2 & \\ & & & \ddots & \ddots & \ddots \end{pmatrix}$$

Matrices, graphs, finite Markov chains, and signal models.

Concepts:

- (1) a square matrix $A \in \mathbb{C}^{n \times n}$
- (2) a weighted graph with n vertices
- (3) a finite Markov chain with n states
- (4) a shift-invariant signal model $(\mathcal{F}, \mathcal{M}, \mathcal{P})$ with $A = M = \mathbb{C}[x] / p(x)$

weighted graph $\xrightleftharpoons{\text{adjacency matrix}}$ matrix A



Equivalence of concepts:

- (a) Matrix \iff weighted graph
- (b) Matrix \iff Markov chain

\rightarrow Note the condition $A \geq 0$, as any matrix $A \in \mathbb{C}^{n \times n}$ can have its rows scaled, so that each has a sum of 1.

- (c) Matrix \iff signal model

Regular model: $A = M = \mathbb{C}[x] / p(x)$
 $\leftarrow M$ uniquely determines $A = \varphi(x)$.

\rightarrow
Lemma: $A \in \mathbb{C}^{n \times n}$. There exists $p(x) \in \mathbb{C}[x]$, $\deg p(x) = n$, and a basis of $\mathbb{C}[x] / p(x)$, such that $\varphi(x) = A$ iff $m_A(x) = p_A(x)$. Then $p(x) = p_A(x)$.

(Reminder: $p_A(x) = \det(xI - A)$ is called a characteristic polynomial of A . $m_A(x)$, a monic polynomial of minimal degree, such that $m_A(A) = 0$, is called a minimal polynomial of A)

Non-regular model: $A \neq M$

What if A is a subalgebra of $\mathbb{C}[X]/p(x)$?

Lemma: $p(x) = \prod_{i=0}^{n-1} (x-d_i)$, $d_i \neq d_j$ ($i \neq j$); $\mathcal{A} = \mathbb{C}[X]/p(x)$, and $g(x) \in \mathcal{A}$.

$$\langle g(x) \rangle_{\text{Alg.}} = \mathcal{A} \iff g(d_i) \neq g(d_j) \quad (i \neq j).$$

Theorem (not in the paper):

Same conditions on $p(x), g(x)$.

$$\dim \langle g(x) \rangle_{\text{Alg.}} = |g(d_0), \dots, g(d_{n-1})|.$$

Example: $p(x) = x^4 - 1$, $g(x) = \frac{x+x^{-1}}{2} = \frac{x+x^{4-1}}{2} = \frac{x+x^3}{2}$.

Lemma: $A \in \mathbb{C}^{n \times n}$:
$$\varphi: \mathbb{C}[X]/m_A(x) \rightarrow \mathbb{C}^{n \times n}$$
$$x \mapsto A$$

φ is a representation of $\mathcal{A} = \mathbb{C}[X]/m_A(x)$, i.e. a homomorphism of algebras.

Lemma: $A \in \mathbb{C}^{n \times n}$. There exists a module $M = \mathbb{C}[X]/p(x)$ (p is separable) with the regular representation φ (w.r.t. suitable basis b), such that $A = \varphi(g(x))$ iff A is diagonalizable.

In this case $\mathcal{A} \cong \mathbb{C}[X]/m_A(x)$.