

Linear Time Encoding of LDPC Codes

Jin Lu, *Member, IEEE*, and José M. F. Moura, *Fellow, IEEE*

Abstract—In this paper, we propose a linear complexity encoding method for arbitrary LDPC codes. We start from a simple graph-based encoding method “label-and-decide.” We prove that the “label-and-decide” method is applicable to Tanner graphs with a hierarchical structure—pseudo-trees—and that the resulting encoding complexity is linear with the code block length. Next, we define a second type of Tanner graphs—the encoding stopping set. The encoding stopping set is encoded in linear complexity by a revised label-and-decide algorithm—the “label-decide-recompute.” Finally, we prove that any Tanner graph can be partitioned into encoding stopping sets and pseudo-trees. By encoding each encoding stopping set or pseudo-tree sequentially, we develop a linear complexity encoding method for general low-density parity-check (LDPC) codes where the encoding complexity is proved to be less than $4 \cdot M \cdot (\bar{k} - 1)$, where M is the number of independent rows in the parity-check matrix and \bar{k} represents the mean row weight of the parity-check matrix.

Index Terms—Encoding stopping set, low-density parity-check (LDPC) codes, linear complexity encoding, pseudo-tree, Tanner graphs.

I. INTRODUCTION

LOW-density parity check (LDPC) codes [1] are excellent error correcting codes with performance close to the Shannon capacity [2]. The key weakness of LDPC codes is their apparently high encoding complexity. The conventional way to encode LDPC codes is to multiply the data words \vec{s} by the code generator matrix \mathbf{G} , i.e., the codewords are $\vec{x} = \mathbf{G} \cdot \vec{s}$. Though the parity-check matrix \mathbf{H} for LDPC codes is sparse, the associated generator matrix \mathbf{G} is not. The encoding complexity of LDPC codes is $\mathcal{O}(n^2)$ where n is the block length of the LDPC code. For moderate-to-high code block length n , this quadratic behavior is very significant and it severely affects the application of LDPC codes. For example, LDPC codes have advantages over turbo codes [3] in almost every aspect except that LDPC codes have $\mathcal{O}(n^2)$ encoding complexity, while turbo codes have $\mathcal{O}(n)$ encoding complexity. It is highly desirable to reduce the $\mathcal{O}(n^2)$ encoding complexity of LDPC codes.

Several authors have addressed the issue of speeding encoding of LDPC codes and, generally speaking, they follow three different paths. The first path designs efficient encoding methods for particular types of LDPC codes. We list a few typical representations. Reference [4] proposes a linear complexity encoding method for cycle codes—LDPC codes with

column weight 2. Reference [5] presents an efficient encoder for quasi-cyclic LDPC codes. In [6], an efficient encoding approach is proposed for Reed–Solomon-type array codes. Reference [7] shows that there exists a linear time encoder for turbo-structured LDPC codes. Reference [8] constructs LDPC codes based on finite geometries and proves that this type of structured LDPC codes can be encoded in linear time. In [9], [11], two families of irregular LDPC codes with cyclic structure and low encoding complexity are designed. In addition, an approximately lower triangular ensemble of LDPC codes [10] was proposed to facilitate almost linear complexity encoding. The above low-complexity encoders are only applicable to a small subset of LDPC codes, and some of the LDPC codes discussed above have performance loss when compared to randomly constructed LDPC codes. The second path borrows the decoder architecture and encodes LDPC codes iteratively on their Tanner graphs [12], [13]. The iterative LDPC encoding algorithm is easy to implement. However, there is no guarantee that iterative encoding will successfully get the codeword. In particular, the iterative encoding method will get trapped at the stopping set. The third path utilizes the sparseness of the parity-check matrix to design a low-complexity encoder. In [14], the authors present an algorithm named “greedy search” that reduces the coefficient of the quadratic term. This encoding method is relatively efficient. Its computation complexity and matrix storage need to be further reduced for most practical applications.

In this paper, we develop an *exact* linear complexity encoding method for arbitrary LDPC codes. We start from two particular Tanner graph structures—“pseudo-tree” and “encoding stopping set”—and prove that both the pseudo-tree and the encoding stopping set LDPC codes can be encoded in linear time. Next, we prove that any LDPC code with maximum column weight three can be decomposed into pseudo-trees and encoding stopping sets. Therefore, LDPC codes with maximum column weight three can be encoded in linear time and the encoding complexity is no more than $2 \cdot M \cdot (\bar{k} - 1)$ where M denotes the number of independent rows of the parity-check matrix and \bar{k} represents the average row weight. Finally, we extend the $\mathcal{O}(n)$ complexity encoder to LDPC codes with arbitrary row weight distributions and column weight distributions. For arbitrary LDPC codes, we achieve $\mathcal{O}(n)$ encoding complexity, not exceeding $4 \cdot M \cdot (\bar{k} - 1)$.

The remainder of the paper is organized as follows. In Section II, we introduce relevant definitions and notation. Section III proposes a simple encoding algorithm “label-and-decide” that directly encodes an LDPC code on its Tanner graph. Section IV presents a particular type of Tanner graph with multiple layers—“pseudo-tree” and proves that any pseudo-tree can be encoded successfully in linear time by the label-and-decide algorithm. Section V studies the complement of the

Manuscript received April 23, 2008; revised March 26, 2009. Current version published December 23, 2009.

J. Lu is with Sun Microsystems, Bloomfield, CO 80021 USA (e-mail: j.lu@sun.com).

J. M. F. Moura is with the Department of Electrical and Computer Engineering, Carnegie Mellon University, Pittsburgh, PA 15213 USA (e-mail: moura@ece.cmu.edu).

Communicated by I. Sason, Associate Editor for Coding Theory.

Digital Object Identifier 10.1109/TIT.2009.2034823

pseudo-tree—“encoding stopping set.” Section VI proves that the encoding stopping set can also be encoded in linear time by an encoding method named “label-decide-recompute.” Section VII demonstrates that any LDPC code with column weight at most three can be decomposed into pseudo-trees and encoding stopping sets. By encoding each pseudo-tree or encoding stopping set sequentially using the label-and-decide or the label-decide-recompute algorithms, we achieve linear complexity encoding for LDPC codes with maximum column weight three. Finally, we extend in this section this linear time encoding method to LDPC codes with arbitrary column weight distributions and row weight distributions. Section VIII concludes the paper.

II. NOTATION

LDPC codes. LDPC codes can be described by their parity-check matrix or their associated Tanner graph [15]. In the Tanner graph, each bit becomes a bit node and each parity-check constraint becomes a check node. If a bit is involved in a parity-check constraint, there is an edge connecting the bit node and the corresponding check node. The degree of a check node in a Tanner graph is equivalent to the number of 1’s in the corresponding row of the parity-check matrix, or, in another words, the row weight of the corresponding row. We will use the term “degree of a check node” and “row weight” interchangeably in this paper. Similarly, the degree of a bit node in a Tanner graph is equivalent to the column weight of the corresponding column of the parity-check matrix, and we will interchangeably use the term “degree of a bit node” and “column weight” in this paper. The LDPC codes discussed in this paper may be irregular, i.e., different columns of the parity-check matrix have different column weights and different rows of the parity-check matrix have different row weights. The parity-check matrix of an LDPC code may not be of full rank. If a row in the parity-check matrix can be written as the binary sums of some other rows in the parity-check matrix, this row is said to be *dependent* on the other rows. Otherwise, it is an *independent* row.

Arithmetic over the binary field. We represent by “ \oplus ” the summation over the binary field, i.e., an XOR operation. For example, $0 \oplus 1 = \text{mod}(0+1, 2) = 1$. Similarly, we have $0 \oplus 0 = 0$, $1 \oplus 0 = 1$, $1 \oplus 1 = 0$. In addition, we have the following $-x = x$ in the binary field. Further, we use the symbol “ $\sim x$ ” to represent the inverse of the value x in the binary field. As an illustration, $\sim 0 = 1$ and $\sim 1 = 0$.

Generalized parity-check equation. A conventional parity-check equation is shown in (1). The right-hand side of the parity-check equation is always 0.

$$x_1 \oplus x_2 \oplus \cdots \oplus x_k = 0. \quad (1)$$

In this paper, we define the *generalized parity-check equation*, as shown in (2)

$$x_1 \oplus x_2 \oplus \cdots \oplus x_k = b. \quad (2)$$

On the right-hand side of (2), b is a constant that can be either 0 or 1.

Let C be a standard parity-check equation. If the values of some of the bits in the left-hand side of C are already known, then C can be equivalently rewritten as a generalized parity-check equation. For example, if the values of the bits $x_{p+1}, x_{p+2}, \dots, x_k$ are known, we move these bits from the left-hand side of (1) to its right-hand side and rewrite it as follows:

$$x_1 \oplus x_2 \oplus \cdots \oplus x_p = x_{p+1} \oplus x_{p+2} \oplus \cdots \oplus x_k = b. \quad (3)$$

Let C_1, C_2, \dots, C_p be p generalized parity-check equations, as shown in (4)

$$\begin{aligned} C_1 &: x_{1,1} \oplus x_{1,2} \oplus \cdots \oplus x_{1,a_1} = b_1 \\ C_2 &: x_{2,1} \oplus x_{2,2} \oplus \cdots \oplus x_{2,a_2} = b_2 \\ &\vdots \\ C_p &: x_{p,1} \oplus x_{p,2} \oplus \cdots \oplus x_{p,a_p} = b_p. \end{aligned} \quad (4)$$

We say C_1, C_2, \dots, C_p are dependent on each other if the corresponding homogeneous equations in (5) are dependent on each other

$$\begin{aligned} x_{1,1} \oplus x_{1,2} \oplus \cdots \oplus x_{1,a_1} &= 0 \\ x_{2,1} \oplus x_{2,2} \oplus \cdots \oplus x_{2,a_2} &= 0 \\ &\vdots \\ x_{p,1} \oplus x_{p,2} \oplus \cdots \oplus x_{p,a_p} &= 0. \end{aligned} \quad (5)$$

From (4) and (5), we derive that

$$b_1 \oplus b_2 \oplus \cdots \oplus b_p = 0 \quad (6)$$

when the p generalized parity-check equations C_1, C_2, \dots, C_p are dependent on each other.

Connected graph. A graph is *connected* if there exists a path from any vertex to any other vertices in the graph. If a graph is not connected, we call it a *disjoint* graph.

Relative complement of a subgraph \mathcal{S} in a Tanner graph \mathcal{G} . Let \mathcal{G} be a Tanner graph and \mathcal{S} be a subgraph of \mathcal{G} , i.e., $\mathcal{S} \subset \mathcal{G}$. We use the symbol $\mathcal{G} \setminus \mathcal{S}$ to denote the subgraph that contains the nodes and edges in \mathcal{G} , but not in \mathcal{S} . For example, let C_1, C_2, \dots, C_k be k check nodes in a Tanner graph \mathcal{G} . The subgraph $\mathcal{G} \setminus \{C_1, C_2, \dots, C_k\}$ represents the remaining graph after deleting check nodes C_1, C_2, \dots, C_k from \mathcal{G} . Assume $\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_k$ are k subgraphs in a Tanner graph \mathcal{G} . The notation $\mathcal{G} \setminus \{\mathcal{G}_1 \cup \mathcal{G}_2 \cup \dots \cup \mathcal{G}_k\}$ represents the subgraph where nodes and edges are in \mathcal{G} , but not in \mathcal{G}_i , $1 \leq i \leq k$.

III. “LABEL-AND-DECIDE” ENCODING ALGORITHM

Initially, Tanner graphs [15] were developed to explain the decoding process for LDPC codes; in fact, they can be used for the encoding of LDPC codes as well [12]. To encode an LDPC code using its Tanner graph, we identify information bits and parity bits through a labeling process on the graph. After determining the information bits and the parity bits, we start by assigning numerical values to the bit nodes labeled as information bits and then in a second step, calculate the missing values of the parity bits sequentially. This encoding approach is named *label-and-decide*. It is described in Algorithm 1.

Algorithm 1 Label-and-decide algorithm

Preprocessing (carry out only once):

Label every bit node either as information bit or parity bit on the Tanner graph.

Encoding:

$Flag \leftarrow 0$;

Get the values of all the bits labeled as information bits;

while there are parity bits undetermined **do**

if there exists one undetermined parity bit x that can be uniquely computed from the values of the information bits and the already determined parity bits **then**

Compute the value of x .

else

$Flag \leftarrow 1$, exit the while loop.

end if

end while

if $Flag = 1$ **then**

Encoding is unsuccessful.

else

Output the encoded codeword.

end if

Example: Fig. 1 shows on the left an LDPC code whose Tanner graph is a tree. Initially, all its bit nodes are unlabeled. First, we randomly pick bit nodes x_1 , x_2 , and x_3 to be information bits. According to the parity-check equation C_1 , the value of bit x_4 depends on the values of the bits x_1 , x_2 , and x_3 such that $x_4 = x_1 \oplus x_2 \oplus x_3$. Therefore, x_4 should be labeled as a parity bit. Similarly, we label bits x_5 , x_6 , x_8 , x_9 as information bits and label bits x_7 , x_{10} as parity bits. We represent information bits by solid circles and parity bits by empty circles. The labeling result is shown on the right in Fig. 1.

By the above labeling process, we decide the systematic component of the codeword $\vec{x} = (x_1 x_2 x_3 x_4 x_5 x_6 x_7 x_8 x_9 x_{10})$ to be $\vec{s} = (x_1 x_2 x_3 x_5 x_6 x_8 x_9)$ and the parity component to be $\vec{p} = (x_4 x_7 x_{10})$. The label-and-decide encoding on the code in Fig. 1 then has the following steps:

- Step 1. Get the values of the information bits $x_1, x_2, x_3, x_5, x_6, x_8, x_9$ from the encoder input.
- Step 2. Compute the parity bit x_4 from the parity-check equation $C_1 : x_4 = x_1 \oplus x_2 \oplus x_3$.
- Step 3. Compute the parity bit x_7 from the parity-check equation $C_2 : x_7 = x_4 \oplus x_5 \oplus x_6$; compute the parity bit x_{10} from the parity-check equation $C_3 : x_{10} = x_4 \oplus x_8 \oplus x_9$.

In fact, any tree code (whose Tanner graph is cycle-free) can be encoded in linear complexity by the label-and-decide algorithm. We will prove this fact in Corollary 2 in Section V. Further, the label-and-decide algorithm can be used to encode a particular type of Tanner graphs with cycles, i.e., the pseudo-tree we propose in the next section.

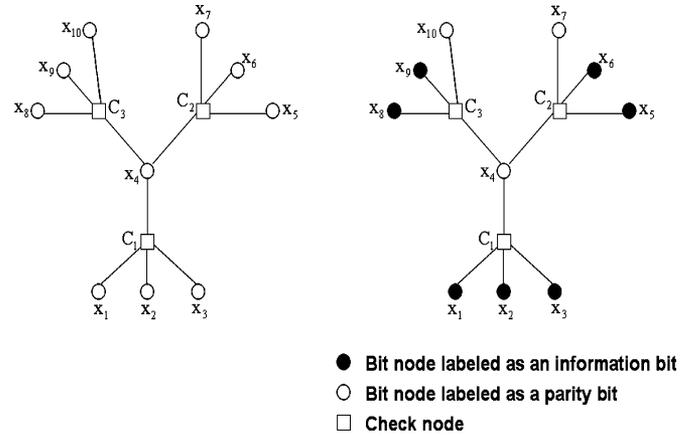


Fig. 1. Left: A Tanner graph. Right: Labeling bit nodes on the Tanner graph shown on the left.

IV. PSEUDO-TREE

A *pseudo-tree* is a connected Tanner graph that satisfies the following conditions (A1) through (A4).

- (A1) It is composed of $2P + 1$ tiers where P is a positive integer. We number these tiers from 1 to $2P + 1$, starting from the top. The $(2i - 1)$ th tier ($i = 1, 2, \dots, P + 1$) contains only bit nodes, while the $(2i)$ th tier ($i = 1, 2, \dots, P$) contains only check nodes.
- (A2) Each bit node in the first tier has degree one and is connected to one and only one check node in the second tier.
- (A3) For each check node C_α in the $(2i)$ th tier, where i can take any value from 1 to P , there is one and only one bit node x_α in the $(2i - 1)$ th tier (immediate upper tier) that connects to C_α , and there are no other bit nodes in the upper tiers that connect to C_α . We call x_α the *parent* of C_α and C_α the *child* of x_α .
- (A4) For each bit node x_β in the $(2i - 1)$ th tier, where i can take any value from 2 to P , there is at most one check node C_β in the $(2i)$ th tier (immediate lower tier) that connects to x_β , and there are no other check nodes in the lower tiers that connect to x_β .

For example, Fig. 2 shows a pseudo-tree with seven tiers. It contains many cycles. Each check node C_i in the pseudo-tree is connected to a unique bit node in the immediate upper tier, while each bit node x_i in the pseudo-tree may connect to multiple check nodes in the upper tiers.

An important characteristic of a pseudo-tree is that it can be encoded in linear complexity by the label-and-decide algorithm. This is proved in the following lemma.

Lemma 1: Any LDPC code whose Tanner graph is a pseudo-tree is linear time encodable.

Proof: Let a pseudo-tree contain $2P + 1$ tiers, N bit nodes, and M check nodes. Condition (A3) guarantees that each check node is connected to one and only one parent bit node in the immediate upper tier. Condition (A4) guarantees that different check nodes are connected to different parent bit nodes. Therefore, there are M parent bit nodes for the check nodes. We label

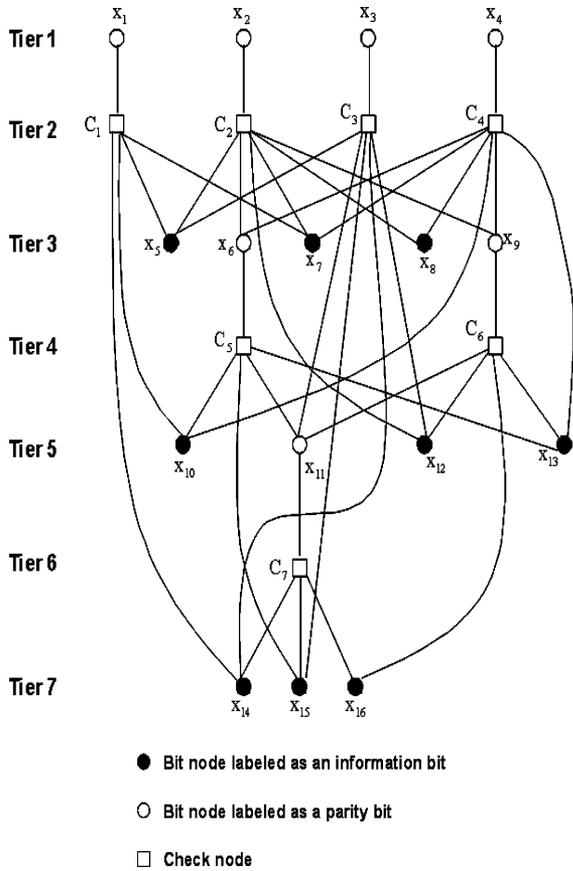


Fig. 2. A pseudo-tree.

these M parent bit nodes as parity bits and the other $N - M$ bit nodes as information bits.

The inputs of the encoder provide the values for all the information bits. The task of the encoder is to compute the values for all the parity bits. Let x_α be an arbitrary parity bit in the $(2i - 1)$ th tier. By conditions (A3) and (A4), there is only one check node C_α in the lower tiers that connects to x_α . The value of x_α is uniquely determined by the parity-check equation represented by C_α . According to condition (A3), all the bit nodes involved in C_α except for x_α are in tiers below the $(2i - 1)$ th tier. Therefore, the value of x_α depends only on the values of the bit nodes below the $(2i - 1)$ th tier. For example, as shown in Fig. 2, parity bit x_9 is the parent bit node of the check node C_6 . From the parity-check equation C_6 , we see that the value of x_9 is computed from the values of x_{11} , x_{12} , x_{16} , and x_{13} , which are located below x_9 . We compute the values of the parity bits tier by tier, starting from the $(2P - 1)$ th tier (bottom tier) and then progressing upwards. Each time we compute the value of a parity bit, we only need the values of those bits (both information bits and parity bits) in lower tiers, which are already known. Hence, this encoding process can proceed. The encoding process is repeated until the values of all the parity bits in the first tier are known.

We evaluate the computation complexity of the above encoding process. Let k_i , $i = 1, 2, \dots, M$, denote the number of bits involved in the i th parity-check equation. The i th parity-check equation determines the value of a parity bit with $(k_i - 2)$

XOR operations. So, $\sum_{i=1}^M (k_i - 2)$ XOR operations are required to obtain all the M parity bits. Let $\bar{k} = \frac{1}{M} \sum_{i=1}^M k_i$ denote the average number of bits in the M parity-check equations, then the encoding complexity is $\mathcal{O}(M(\bar{k} - 2))$. For LDPC codes with uniform row weight k , the encoding complexity is $\mathcal{O}(M(k - 2))$. The above analysis shows that the encoding process is accomplished in linear time. This completes the proof. \square

The linear-complexity encoding process described in the proof of Lemma 1 is summarized in Algorithm 2.

Algorithm 2 Linear-complexity encoding algorithm for a pseudo-tree with $2P + 1$ tiers.

Preprocessing:

Label the parent bit nodes in the pseudo-tree as parity bits and the other bit nodes as information bits.

Encoding:

Get the values of all the information bits from the encoder input.

for $i = P$ to 1 **STEP-1 do**

Compute the values of all the parity bits in tier $2i - 1$ based on the values of the bits below the $(2i - 1)$ th tier.

end for

Output the encoded codeword.

We look at an example. We encode the pseudo-tree in Fig. 2 as follows:

- Step 1. Determine the values of all the information bits x_{14} , x_{15} , x_{16} , x_{10} , x_{12} , x_{13} , x_5 , x_7 , and x_8 .
 - Step 2. Compute the parity bit x_{11} from the parity-check equation C_7 : $x_{11} = x_{14} \oplus x_{15} \oplus x_{16}$.
 - Step 3. Compute the parity bit x_6 from the parity-check equation C_5 : $x_6 = x_{10} \oplus x_{15} \oplus x_{11} \oplus x_{13}$; compute the parity bit x_9 from the parity-check equation C_6 : $x_9 = x_{11} \oplus x_{12} \oplus x_{16} \oplus x_{13}$.
 - Step 4. Compute the parity bits x_1 , x_2 , x_3 , and x_4 in the first tier by the parity-check equations C_1 , C_2 , C_3 , and C_4 , respectively: $x_1 = x_{14} \oplus x_{10} \oplus x_5 \oplus x_7$, $x_2 = x_5 \oplus x_6 \oplus x_{12} \oplus x_7 \oplus x_8 \oplus x_9$, $x_3 = x_5 \oplus x_{11} \oplus x_{15} \oplus x_{14} \oplus x_{12}$, $x_4 = x_6 \oplus x_7 \oplus x_8 \oplus x_{10} \oplus x_9 \oplus x_{13}$.
- The above encoding process requires only 25 XOR operations.

V. ENCODING STOPPING SET

An *encoding stopping set* in a Tanner graph is a connected subgraph such that:

- (B1) If a check node C is in an encoding stopping set, then all the bit nodes involved in C and the edges that are incident on C are also in the encoding stopping set.
- (B2) Any bit node in an encoding stopping set is connected to at least two check nodes in the encoding stopping set.
- (B3) All the check nodes contained in an encoding stopping set are independent of each other, i.e., any parity-check equation cannot be represented as the binary sums of other parity-check equations.

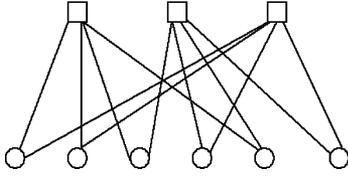


Fig. 3. A pseudo-encoding stopping set.

The number of check nodes in an encoding stopping set is called its size. If a connected Tanner graph satisfies conditions (B1) and (B2) but not condition (B3), we call this Tanner graph a *pseudo-encoding stopping set*. For example, the Tanner graph shown in Fig. 3 is not an encoding stopping set but a pseudo-encoding stopping set since it satisfies conditions (B1) and (B2) but not condition (B3). The Tanner graph shown in Fig. 4 is an encoding stopping set. Its size is 9. Every bit node in this encoding stopping set has degree greater than or equal to 2, and every check node is independent of each other. Please note that the “encoding stopping set” defined in this paper is different from the “stopping set” defined in [16]. Stopping sets are used for the finite-length analysis of LDPC codes on the binary erasure channel, while encoding stopping sets are used here to develop efficient encoding methods for LDPC codes. From the above definitions of pseudo-tree and encoding stopping set, we have the following lemma.

Lemma 2: Any pseudo-tree or union of pseudo-trees does not contain encoding stopping sets.

Proof: See Appendix A.

We will show next that the label-and-decide algorithm cannot successfully encode encoding stopping sets.

Theorem 1: An encoding stopping set cannot be encoded successfully by the label-and-decide algorithm.

Proof: Let \mathcal{E}_f be an encoding stopping set and suppose \mathcal{E}_f can be encoded successfully by the label-and-decide algorithm. Let x_α be the last parity bit being determined during the encoding process. Since \mathcal{E}_f is an encoding stopping set, x_α is connected to at least two check nodes C_β and C_γ by condition (B2). Further, by condition (B3), all the check nodes in \mathcal{E}_f , including C_β and C_γ , are independent of each other. Hence, for certain encoder inputs, C_β and C_γ provide different values for the parity bit x_α . This contradicts the fact that every parity bit can be uniquely determined successfully by the label-and-decide algorithm. Hence, the label-and-decide algorithm cannot encode an encoding stopping set. This completes the proof. \square

Conversely, if a Tanner graph does not contain any encoding stopping set, there must exist a linear complexity encoder for the corresponding code.

Theorem 2: If a Tanner graph \mathcal{G} does not contain any encoding stopping set, then it can be encoded in linear time by the label-and-decide algorithm.

Proof: We first delete all redundant check nodes (i.e., dependent on other check nodes) from the Tanner graph \mathcal{G} . Next, we restrict our attention to the case that \mathcal{G} is a connected graph. We will show that \mathcal{G} can be equivalently transformed into a pseudo-tree if it is free of any encoding stopping set. Since \mathcal{G} does not contain any encoding stopping set, \mathcal{G} itself is not an

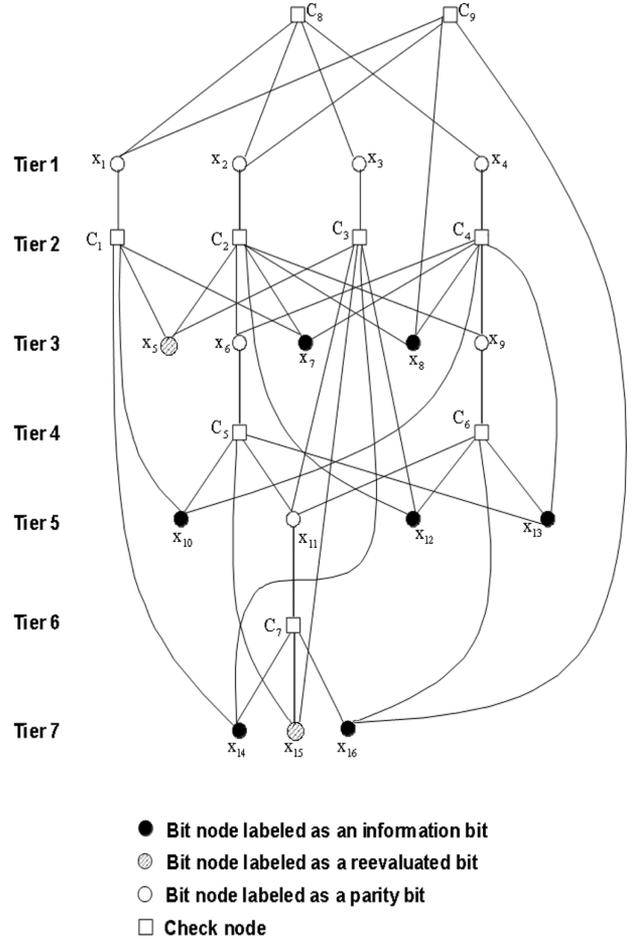


Fig. 4. An encoding stopping set that contains a pseudo-tree shown in Fig. 2.

encoding stopping set. Hence, there exist some degree-one bit nodes in \mathcal{G} . We generate a multilayer graph \mathcal{T} and place those degree-one bit nodes in the first tier of \mathcal{T} . Next, the check nodes that connect to the degree-one bit nodes in the first tier of \mathcal{T} are placed in the second tier of \mathcal{T} . Notice that there exist at least one bit node x_α in $\mathcal{G} \setminus \mathcal{T}$ such that x_α connects to at most one check node in $\mathcal{G} \setminus \mathcal{T}$. This statement is true. Otherwise, $\mathcal{G} \setminus \mathcal{T}$ becomes an encoding stopping set, which contradicts the fact that \mathcal{G} does not contain any encoding stopping set. We pick all the bit nodes in $\mathcal{G} \setminus \mathcal{T}$ that connect to at most one check node in $\mathcal{G} \setminus \mathcal{T}$ and place them in the third tier of \mathcal{T} . Correspondingly, those check nodes in $\mathcal{G} \setminus \mathcal{T}$ that connect to the bit nodes in the third tier of \mathcal{T} are placed in the fourth tier of \mathcal{T} . Each time we find bit nodes in $\mathcal{G} \setminus \mathcal{T}$ that connect to at most one check node in $\mathcal{G} \setminus \mathcal{T}$, we place those bit nodes in a new tier $2s + 1$ of \mathcal{T} and place the check nodes connecting to those bit nodes in the following new tier $2s + 2$ of \mathcal{T} . We continue finding such bit nodes and increasing tiers till all the nodes in \mathcal{G} are included in \mathcal{T} . Up to now, the multilayer structure constructed so far satisfies the conditions (A1), (A2), and (A4). Condition (A3) may fail to be satisfied. For example, as shown on the top in Fig. 5, the check node C_4 in tier 4 is connected to two bit nodes x_6 and x_7 in tier 3, which contradicts condition (A3). To satisfy condition (A3), we further adjust the positions of the bit nodes. If a check node in tier $2i$ is connected to k bit nodes in the upper tiers of \mathcal{T} , we pick

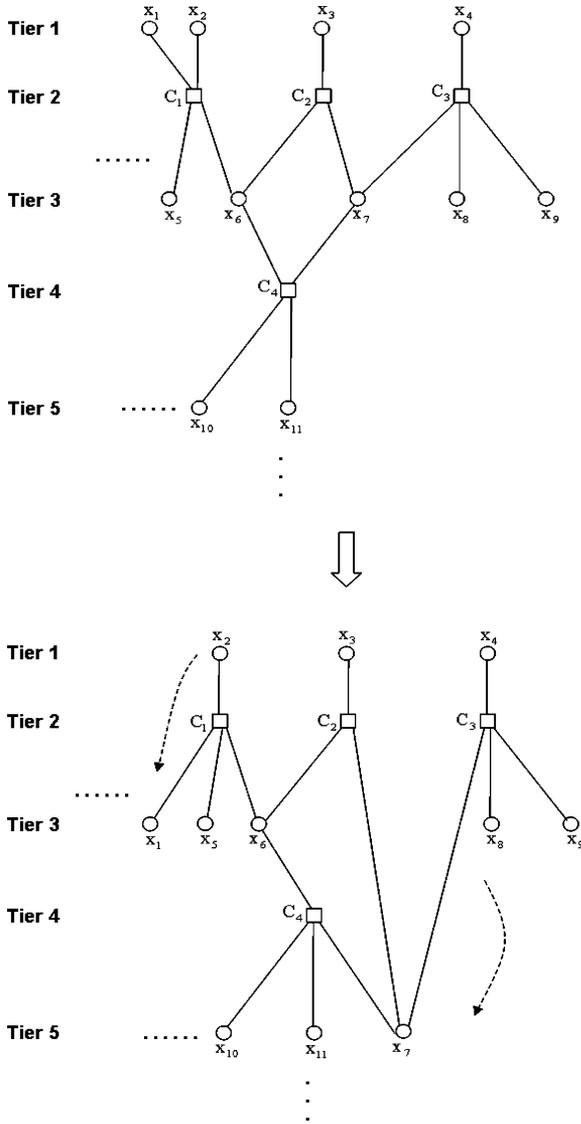


Fig. 5. Top: A multilayer structure but not a pseudo-tree. (Note that C_4 has two parents x_6 and x_7 and C_1 has two parents x_1 and x_2 .) Bottom: The pseudo-tree that evolves from the multilayer structure shown on the top.

one bit node in tier $2i - 1$ from these k bit nodes and leave its position unchanged. Next, we drag the other $k - 1$ bit nodes from their initial positions in tier $2i - 1$ to the $(2i + 1)$ th tier. To illustrate, let us focus on Fig. 5 again. We drag the bit node x_7 from tier 3 to tier 5 and drag the bit node x_1 from tier 1 to tier 3. The newly formed graph is shown at the bottom in Fig. 5, which follows condition (A3). By tuning the positions of the bit nodes in this way, the resulting hierarchical graph satisfies conditions (A1) to (A4). In this way, we transform \mathcal{G} into a pseudo-tree. By Lemma 1, a pseudo-tree is linear time encodable. Therefore, the encoding complexity of \mathcal{G} is $\mathcal{O}(M)$ where M denotes the number of independent check nodes contained in \mathcal{G} .

We now prove the case that \mathcal{G} is a disjoint graph. Let \mathcal{G} contain p connected subgraphs: $\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_p$. By the above analysis, the complexity of encoding \mathcal{G}_i is $\mathcal{O}(M_i), i = 1, 2, \dots, p$, where M_i denotes the number of independent check nodes contained in

\mathcal{G}_i . Since $\mathcal{G} = \mathcal{G}_1 \cup \mathcal{G}_2 \cup \dots \cup \mathcal{G}_p$, then the encoding complexity of \mathcal{G} is $\sum_{i=1}^p \mathcal{O}(M_i) = \mathcal{O}(\sum_{i=1}^p M_i) = \mathcal{O}(M)$ where M is the number of independent check nodes in \mathcal{G} . This completes the proof. \square

In the proof of Theorem 2, we detailed the process of transforming a connected Tanner graph that is free of any encoding stopping sets into a pseudo-tree. We further summarize the above transformation process in Algorithm 3.

Algorithm 3 Transform a connected Tanner graph \mathcal{G} into a pseudo-tree \mathcal{T} .

```

Remove all the redundant check nodes from the Tanner
graph  $\mathcal{G}$ .
 $\mathcal{T} = \phi$ ;  $Flag \leftarrow 0$ ;  $i = 1$ .
if there exist degree-one bit nodes in  $\mathcal{G}$  then
    Place all the degree-one bit nodes in the first tier of  $\mathcal{T}$ .
    Place all the check nodes that connect to the degree-one
    bit nodes in the second tier of  $\mathcal{T}$ .
else
     $Flag \leftarrow 1$ .
end if
while  $Flag = 0$  and  $\mathcal{G} \neq \mathcal{T}$  do
    if there exist bit nodes in  $\mathcal{G} \setminus \mathcal{T}$  that connect to at most
    one check node in  $\mathcal{G} \setminus \mathcal{T}$  then
        Pick all the bit nodes in  $\mathcal{G} \setminus \mathcal{T}$  that connect to at most
        one check node in  $\mathcal{G} \setminus \mathcal{T}$  and place them in a new tier
         $2i + 1$  of  $\mathcal{T}$ .
        Pick all those check nodes in  $\mathcal{G} \setminus \mathcal{T}$  that connect to the
        bit nodes in the tier  $2i + 1$  of  $\mathcal{T}$  and place them in a
        new tier  $2i + 2$  of  $\mathcal{T}$ .
    else
         $Flag \leftarrow 1$ .
    end if
     $i = i + 1$ .
end while
if  $Flag = 0$  then
    for  $s = 1$  to  $i$  do
        while a check node in tier  $2s$  is connected to  $k$ 
        ( $k > 1$ ) bit nodes in the upper tiers of  $\mathcal{T}$  do
            Pick one bit node in tier  $2s - 1$  from these  $k$  bit
            nodes and leave its position unchanged.
            Drag the other  $k - 1$  bit nodes from their initial
            positions in tier  $2s - 1$  to the  $(2s + 1)$ th tier, as
            shown in Fig. 5.
        end while
    end for
    Output the generated pseudo-tree  $\mathcal{T}$  derived from the
    original Tanner graph  $\mathcal{G}$ .
else
    The Tanner graph  $\mathcal{G}$  can NOT be transformed into a
    pseudo-tree.
end if

```

From Theorem 2, we easily derive the following four corollaries.

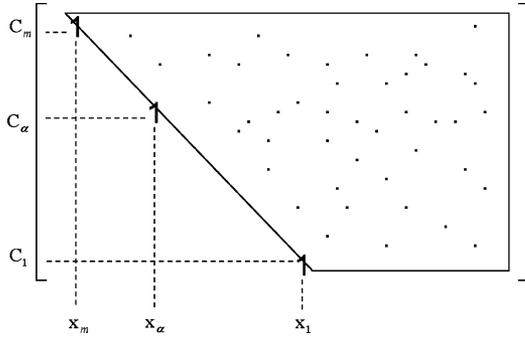


Fig. 6. A parity-check matrix in upper triangular form.

Corollary 1: If a Tanner graph does not contain any encoding stopping set, then it can be represented by a pseudo-tree or a union of pseudo-trees.

Proof: The proof of Corollary 1 can be found in the proof of Theorem 2. \square

Corollary 2: The label-and-decide algorithm can encode any tree LDPC codes (whose Tanner graphs are cycle-free) with linear complexity.

Proof: Let \mathcal{T} be the Tanner graph of a tree LDPC code and \mathcal{S} be an arbitrary subgraph of \mathcal{T} . Since the Tanner graph \mathcal{T} is a tree, its subgraph \mathcal{S} is either a tree or a union of trees. Therefore, the graph \mathcal{S} contains at least one bit leaf node with degree one. Since the graph \mathcal{S} contains a degree-one bit node, \mathcal{S} cannot be an encoding stopping set. Since no subgraph of \mathcal{T} is an encoding stopping set, by Theorem 2, the tree code \mathcal{T} can be encoded in linear complexity by the label-and-decide algorithm. This completes the proof. \square

Corollary 3: A regular LDPC code with column weight 2 (cycle code) can be encoded in linear complexity by the label-and-decide algorithm.

Proof: We prove Corollary 3 by showing that a cycle code does not contain any encoding stopping set. Assume the cycle code contains an encoding stopping set \mathcal{E}_f . By the definition of cycle code and condition (B2), all the bit nodes in \mathcal{E}_f have uniform degree two. It follows that the binary sum of all the parity-check equations in \mathcal{E}_f is a vector of 0's. Then, at least one check node in \mathcal{E}_f is dependent on the other check nodes. This contradicts condition (B3) that all the check nodes in an encoding stopping set are independent of each other. Hence, a cycle code does not contain any encoding stopping set. By Theorem 2, a cycle code is linear time encodable by the label-and-decide algorithm. This completes the proof. \square

An alternative proof can be found in [4].

Corollary 4: Let \mathbf{H} be the parity-check matrix of an LDPC code. If \mathbf{H} can be transformed into an upper triangular matrix \mathbf{U} by row and column permutations, then the LDPC code can be encoded in linear time by the label-and-decide algorithm.

Proof: We label the rows of the upper triangular matrix \mathbf{U} one by one as C_1, C_2, \dots, C_m , from the bottom to the top, as shown in Fig. 6. We notice that if $i > j$, then there exists at least one bit that is involved in C_i but not in C_j . Assume the Tanner graph of the code contains an encoding stop-

ping set \mathcal{E}_f that contains check nodes $C_{i_1}, C_{i_2}, \dots, C_{i_p}$. Let $q = \max(i_1, i_2, \dots, i_p)$. There exists at least one bit node x_q in \mathcal{E}_f that only connects to C_q . This contradicts the fact that every bit node in an encoding stopping set is connected to at least two check nodes in the encoding stopping set. Hence, \mathcal{E}_f is not an encoding stopping set. Since the Tanner graph of the LDPC code does not contain any encoding stopping set, by Theorem 2 it is linear time encodable. This completes the proof. \square

Theorems 1 and 2 show that encoding stopping sets prevent the application of the label-and-decide algorithm. However, we will show in the next section that encoding stopping sets can also be encoded in linear complexity.

VI. LINEAR COMPLEXITY ENCODING APPROACH FOR ENCODING STOPPING SETS

Let \mathcal{E}_f be an encoding stopping set. We say \mathcal{E}_f is a k -fold-constraint encoding stopping set if the following two conditions hold.

- (C1) There exist k check nodes C_1, C_2, \dots, C_k in \mathcal{E}_f such that $\mathcal{E}_f \setminus \{C_1, C_2, \dots, C_k\}$ does not contain any encoding stopping set. We call the k check nodes C_1, C_2, \dots, C_k key check nodes. We always specify the k key check nodes C_1, C_2, \dots, C_k when defining a k -fold-constraint encoding stopping set.
- (C2) For any $k - 1$ check nodes C_1, C_2, \dots, C_{k-1} in \mathcal{E}_f , $\mathcal{E}_f \setminus \{C_1, C_2, \dots, C_{k-1}\}$ contains an encoding stopping set.

The notation $\mathcal{E}_f \setminus \{C_1, C_2, \dots, C_k\}$ denotes the remaining graph after deleting check nodes C_1, C_2, \dots, C_k from \mathcal{E}_f . Fig. 4 shows a twofold-constraint encoding stopping set with key check nodes C_8 and C_9 . After deleting the two key check nodes C_8 and C_9 from this encoding stopping set, the Tanner graph turns into a pseudo-tree, see Fig. 2. We will focus on one-fold-constraint and twofold-constraint encoding stopping sets in this paper, since we will show later that all types of LDPC codes can be decomposed into onefold or twofold constraint encoding stopping sets and pseudo-trees.

Let us first look at a twofold-constraint encoding stopping set \mathcal{E}_f with two key check nodes C_α and C_β . The twofold-constraint encoding stopping set \mathcal{E}_f has size M . By definition, the subgraph $\mathcal{E}_f \setminus \{C_\alpha, C_\beta\}$ does not contain any encoding stopping set. Therefore, we can transform the subgraph $\mathcal{E}_f \setminus \{C_\alpha, C_\beta\}$ into a pseudo-tree \mathcal{T} by Algorithm 3 and then encode \mathcal{T} in linear complexity. Based on the above analysis, we encode the twofold-constraint encoding stopping set \mathcal{E}_f in three steps.

In the first step, we encode $\mathcal{E}_f \setminus \{C_\alpha, C_\beta\}$ using the label-and-decide algorithm according to Theorem 2. During encoding, $M - 2$ bit nodes are labeled as parity bits and the remaining bit nodes are labeled as information bits. In the above encoding process, if we change the value of an information bit x^* and keep the values of all the other information bits unchanged, some parity bits x_1, x_2, \dots, x_q will also change their values. We say that the parity bits x_1, x_2, \dots, x_q are affected by the bit x^* .

In the second step, we verify the two key check nodes C_α and C_β based on the bit values acquired in Step 1. For convenience, we first define the value of a key check node as follows. Let a key check node C_α connect to k bit nodes x_1, x_2, \dots, x_k . The

binary sum $x_1 \oplus x_2 \oplus \dots \oplus x_k$ is defined to be the *value* of the check node C_α . If the parity-check equation associated with a key check node C_α is satisfied, then the value of the key check node C_α is 0. Otherwise, the value of the key check node C_α is 1. If the values of the two key check nodes C_α and C_β are both 0, the encoding results acquired in Step 1 are reliable. If at least one of the two key check nodes C_α and C_β has value 1, then the encoding results acquired in Step 1 need correction. To correct the previously obtained encoding results, we notice that the existence of the key check nodes C_α and C_β indicates that two bits x_γ and x_δ that were previously labeled as information bits are actually parity bits, and their values are determined by C_α and C_β . We call the two bits x_γ and x_δ *reevaluated bits*.

The reevaluated bits x_γ and x_δ satisfy the following three conditions.

- (D1) If x_γ changes its value while x_δ and other information bits keep their values unchanged, then the value of the key check node C_α must also be changed. We say that C_α is affected by x_γ . Although C_α may not directly connect to x_γ , C_α is affected by x_γ through other check nodes and parity bits.
- (D2) If x_δ changes its value while x_γ and other information bits keep their values unchanged, then the value of the key check node C_β must also be changed. We say that C_β is affected by x_δ .
- (D3) If x_γ and x_δ both change their values while the other information bits keep their values unchanged, then the value of at least one of the two key check nodes C_α and C_β is changed.

Since C_α , C_β , and the other check nodes in \mathcal{E}_f are independent of each other, there must exist bit nodes x_γ and x_δ that satisfy conditions (D1) to (D3). An algorithm for finding reevaluated bits x_γ and x_δ from a twofold-constraint encoding stopping set is presented in Appendix B. We also prove the validness of the algorithm in Appendix B. Notice that the workload to find the two reevaluated bits is a preprocessing step that is carried out only once. Assume in Step 1 that x_γ and x_δ are randomly assigned initial values x_γ^0 and x_δ^0 , respectively. If the parity-check equations C_α and C_β are both satisfied, the initial values x_γ^0 and x_δ^0 are the correct values for x_γ and x_δ . If C_α , or C_β , or both, are not satisfied, we need to recompute the values of x_γ and x_δ from the values of the key check nodes C_α and C_β . Let $\Delta x_\gamma = \tilde{x}_\gamma - x_\gamma^0$ and $\Delta x_\delta = \tilde{x}_\delta - x_\delta^0$ where \tilde{x}_γ and \tilde{x}_δ are the correct values of x_γ and x_δ , respectively, and let \tilde{C}_α and \tilde{C}_β be the values of the key check nodes C_α and C_β , respectively. If C_α is affected by x_γ alone, C_β is affected by both x_γ and x_δ , we derive the following equations:

$$\begin{aligned} \Delta x_\gamma &= -\tilde{C}_\alpha = \tilde{C}_\alpha \\ \Delta x_\gamma \oplus \Delta x_\delta &= -\tilde{C}_\beta = \tilde{C}_\beta. \end{aligned} \quad (7)$$

If C_α is affected by both x_γ and x_δ and C_β is affected by x_δ alone, we derive the following equations:

$$\begin{aligned} \Delta x_\gamma \oplus \Delta x_\delta &= -\tilde{C}_\alpha = \tilde{C}_\alpha \\ \Delta x_\delta &= -\tilde{C}_\beta = \tilde{C}_\beta. \end{aligned} \quad (8)$$

If C_α is affected by x_γ alone and C_β is affected by x_δ alone, we have the following equations:

$$\begin{aligned} \Delta x_\gamma &= -\tilde{C}_\alpha = \tilde{C}_\alpha \\ \Delta x_\delta &= -\tilde{C}_\beta = \tilde{C}_\beta. \end{aligned} \quad (9)$$

From (7)–(9), we can get the correct values of x_γ and x_δ . Notice that, condition (D3) prevents the case that C_α is affected by both x_γ and x_δ and C_β is also affected by both x_γ and x_δ .

Algorithm 4 Determine the parity bits in a twofold-constraint encoding stopping set \mathcal{E}_f that are affected by the reevaluated bits x_γ and x_δ . The two key check nodes of \mathcal{E}_f are C_α and C_β .

Use algorithm 3 to transform $\mathcal{E}_f \setminus \{C_\alpha, C_\beta\}$ into a pseudo-tree \mathcal{T} . Assume the reevaluated bit x_γ is in the $(2i - 1)$ th tier of \mathcal{T} and the reevaluated bit x_δ is in the $(2k - 1)$ th tier of \mathcal{T} .

for $d = i - 1$ to 1 **STEP-1 do**

for Each parity bit node in tier $2d - 1$ of \mathcal{T} **do**

if the child (a check node) of a parity bit node x is connected to x_γ and is also connected to an even number (including 0) of parity bits that are affected by x_γ and are located below the $(2d - 1)$ th tier **then**

Label x as a parity bit that is affected by x_γ .

else if the child of the parity bit node x is not connected to x_γ but is connected to an odd number of parity bits that are affected by x_γ and are located below the $(2d - 1)$ th tier **then**

Label x as a parity bit that is affected by x_γ .

else

The parity bit x is not affected by x_γ .

end if

end for

end for

for $d = k - 1$ to 1 **STEP-1 do**

for Each parity bit node in tier $2d - 1$ of \mathcal{T} **do**

if the child (a check node) of a parity bit node x is connected to x_δ and is also connected to an even number (including 0) of parity bits that are affected by x_δ and are located below the $(2d - 1)$ th tier **then**

Label x as a parity bit that is affected by x_δ .

els if the child of the parity bit node x is not connected to x_δ but is connected to an odd number of parity bits that are affected by x_δ and are located below the $(2d - 1)$ th tier **then**

Label x as a parity bit that is affected by x_δ .

else

The parity bit x is not affected by x_δ .

end if

end for

end for

Output the labels (whether a parity bit is affected by x_γ , by x_δ , or by both, or by neither) of all the parity bits.

In the third step, we determine the parity bits x_1, x_2, \dots, x_q that are affected by the reevaluated bits x_γ and x_δ . We provide Algorithm 4 to find those parity bits x_1, x_2, \dots, x_q that are

affected by the reevaluated bits x_γ and x_δ . The output of Algorithm 4 may label a parity bit as being affected by x_γ alone, by x_δ alone, by both x_γ and x_δ , or by neither x_γ nor x_δ . Next, we recompute those parity bits x_1, x_2, \dots, x_q that are affected by x_γ and/or x_δ based on the correct values of x_γ and x_δ . This encoding method is named *label-decide-recompute* and is described in Algorithm 5.

Algorithm 5 Label-decide-recompute algorithm for a twofold-constraint encoding stopping set \mathcal{E}_f with two key check nodes C_α and C_β . \mathcal{E}_f contains M check nodes.

Preprocessing (carry out only once):

Use Algorithm 11 to pick two information bits x_γ and x_δ that satisfy conditions (D1) to (D3) as reevaluated bits.

Use Algorithm 4 to determine the parity bits $x_{p_1}, x_{p_2}, \dots, x_{p_s}$ that are affected by x_γ and/or x_δ .

Encoding:

Fill the values of the information bits except for x_γ and x_δ ;

Assign $x_\gamma = 0$ and $x_\delta = 0$;

Encode $\mathcal{E}_f \setminus \{C_\alpha, C_\beta\}$ using Algorithm 2. Compute the values of the $M - 2$ parity bits;

Compute the values \widetilde{C}_α and \widetilde{C}_β of the key check nodes C_α and C_β , respectively;

if $\widetilde{C}_\alpha \neq 0$ **AND/OR** $\widetilde{C}_\beta \neq 0$ **then**

Recompute the values of x_γ and x_δ from \widetilde{C}_α and \widetilde{C}_β by (7)–(9);

for $i = 1$ to s **do**

Recompute the value of the parity bit x_{p_i} based on the new values of x_γ and x_δ ;

end for

end if

Output the encoding result.

Next, we analyze the computation complexity of the label-decide-recompute algorithm when encoding a twofold-constraint encoding stopping set with size M . Every check node except for the two key check nodes C_α and C_β are computed at most twice in the label-decide-recompute encoding (label-and-decide step and recompute step) while the values of the two key check nodes C_α and C_β need to be computed only once. In addition, we may need one extra XOR operation to compute the two reevaluated bits x_γ and x_δ by (7)–(9). Hence, the encoding complexity of the label-decide-recompute algorithm is less than or equal to $2 \cdot \sum_{i=1}^{M-2} (k_i - 2) + (k_\alpha - 1) + (k_\beta - 1) + 1$, where k_i , $1 \leq i \leq M - 2$, are the degrees of the check nodes other than C_α , C_β and k_α , k_β are the degrees of the check nodes C_α and C_β , respectively. The encoding complexity of the label-decide-recompute algorithm can be further simplified to be less than $2 \cdot M \cdot (\bar{k} - 1)$ where M is the number of check nodes in the encoding stopping set and \bar{k} is the average number of bit nodes involved in each check node in the encoding stopping set. This shows that the label-decide-recompute algorithm encodes any twofold-constraint encoding stopping set in linear time. The preprocessing (determining reevaluated bits, and parity bits affected by the reevaluated bits) is done offline and does not count towards encoder complexity.

We look at an example. Fig. 4 shows a twofold-constraint encoding stopping set \mathcal{E}_f with key check nodes C_8 and C_9 . After deleting the two key check nodes C_8 and C_9 , \mathcal{E}_f becomes the pseudo-tree shown in Fig. 2. Next, we determine the two reevaluated bits following Algorithm 11. We represent the two key check nodes C_8 and C_9 as functions of the information bits as follows:

$$C_8 = x_5 \oplus x_7 \oplus x_{13} \oplus x_{14} \oplus x_{16} \quad (10)$$

$$C_9 = x_{14} \oplus x_{15} \quad (11)$$

From (10) and (11), we see that the value of the bit node x_5 only affects key check node C_8 and the value of the bit node x_{15} only affects key check node C_9 . The two bit nodes x_5 and x_{15} satisfy conditions (D1) to (D3). Hence, we can choose the two bits x_5 and x_{15} as reevaluated bits (there exist other options of the reevaluated bits).

After determining the reevaluated bits, we use Algorithm 4 to find the parity bits that are affected by the reevaluated bits x_5 and x_{15} . We start from tier 5, the parity bit x_{11} is affected by the reevaluated bit x_{15} . In tier 3, the parity bit x_9 is also affected by x_{15} . However, since the parity bit x_6 has child C_5 and C_5 is connected to both x_{15} and the parity bit x_{11} that is affected by x_{15} , the parity bit x_6 is not affected by x_{15} . Similarly, in tier 1, we determine that the parity bits x_2 and x_4 are affected by x_{15} while the parity bits x_1 and x_3 are not affected by x_{15} . In the same way, we label the parity bits x_1, x_2 , and x_3 as being affected by the reevaluated bit x_5 while the parity bit x_4 is not affected by x_5 . We notice that the parity bit x_2 is affected by both x_{15} and x_5 while the parity bit x_6 is affected by neither x_{15} nor x_5 .

After finishing the above preprocessing, we use the label-decide-recompute algorithm to encode \mathcal{E}_f as follows.

- Step 1. Assign $x_5 = 0$ and $x_{15} = 0$. Encode the pseudo-tree part following the procedures in Section IV.
- Step 2. Compute the values of the key check nodes C_8 and C_9 , e.g., $\widetilde{C}_8 = x_1 \oplus x_2 \oplus x_3 \oplus x_4$ and $\widetilde{C}_9 = x_1 \oplus x_2 \oplus x_8 \oplus x_{16}$.
- Step 3a. If $\widetilde{C}_8 = 0$ and $\widetilde{C}_9 = 0$, stop encoding and output the codeword $[x_1 x_2 \dots x_{16}]$.
- Step 3b. If $\widetilde{C}_8 = 1$ and/or $\widetilde{C}_9 = 1$, recompute the values of x_5 and x_{15} as follows: $x_5 = \widetilde{C}_8$ and $x_{15} = \widetilde{C}_9$, where \widetilde{C}_8 and \widetilde{C}_9 are the values of the parity-check equations C_8 and C_9 , respectively. Recompute the parity bits $x_{11}, x_9, x_1, x_2, x_3$, and x_4 based on the new values of x_5 and x_{15} . Output the codeword $[x_1 x_2 \dots x_{16}]$.

The label-decide-recompute algorithm can be further simplified. We restudy the third step of the label-decide-recompute method. Assume x_1, x_2, \dots, x_q are the parity bits whose values need to be updated. In order to get the new values of the parity bits x_1, x_2, \dots, x_q , we need to recompute those parity-check equations that involve x_1, x_2, \dots, x_q . In fact, instead of recomputing the parity-check equations involving parity bits x_1, x_2, \dots, x_q , we can directly flip the values of the parity bits x_1, x_2, \dots, x_q since in the binary field the value of a bit is either 0 or 1.

For example, if the correct value of the reevaluated bit x_γ is different from its originally assigned value x_γ^0 , we simply flip the values of those parity bits that are affected by x_γ . We name the above encoding method *label-decide-flip* and describe it in Algorithm 6. The encoding complexity of Algorithm 6 is at most $M \cdot (\bar{k} - 1)$ XOR operations plus two vector flipping operations. We, again, look at an example. The twofold-constraint encoding stopping set shown in Fig. 4 can be encoded by Algorithm 6 as follows.

Algorithm 6 Label-decide-flip algorithm for a twofold-constraint encoding stopping set \mathcal{E}_f with two key check nodes C_α and C_β . \mathcal{E}_f contains M check nodes.

Preprocessing (carry out only once):

Use Algorithm 11 to pick two information bits x_γ and x_δ that satisfy conditions (D1) to (D3) as reevaluated bits.

Use Algorithm 4 to determine the parity bits $x_{u_1}, x_{u_2}, \dots, x_{u_r}$ that are affected by x_γ alone and group $x_{u_1}, x_{u_2}, \dots, x_{u_r}$ in a vector $\vec{X}_\gamma = [x_{u_1} \ x_{u_2} \ \dots \ x_{u_r}]$.

Use Algorithm 4 to determine the parity bits $x_{p_1}, x_{p_2}, \dots, x_{p_s}$ that are affected by x_δ alone and group $x_{p_1}, x_{p_2}, \dots, x_{p_s}$ in a vector $\vec{X}_\delta = [x_{p_1} \ x_{p_2} \ \dots \ x_{p_s}]$.

Use Algorithm 4 to determine the parity bits $x_{q_1}, x_{q_2}, \dots, x_{q_t}$ that are affected by both x_γ and x_δ and group $x_{q_1}, x_{q_2}, \dots, x_{q_t}$ in a vector $\vec{X}_\epsilon = [x_{q_1} \ x_{q_2} \ \dots \ x_{q_t}]$.

Encoding:

Fill the values of the information bits except for x_γ and x_δ ;
Assign $x_\gamma = 0$ and $x_\delta = 0$;

Encode $\mathcal{E}_f \setminus \{C_\alpha, C_\beta\}$ using Algorithm 2. Compute the values of the $M - 2$ parity bits;

Compute the values \tilde{C}_α and \tilde{C}_β of the parity-check equations C_α and C_β , respectively;

if $\tilde{C}_\alpha \neq 0$ **AND/OR** $\tilde{C}_\beta \neq 0$ **then**

 Recompute the values of x_γ and x_δ from \tilde{C}_α and \tilde{C}_β by (7)–(9);

if $x_\gamma = 1$ **AND** $x_\delta = 0$ **then**

 Flip the vectors \vec{X}_γ and \vec{X}_ϵ .

else if $x_\gamma = 0$ **AND** $x_\delta = 1$ **then**

 Flip the vectors \vec{X}_δ and \vec{X}_ϵ .

else if $x_\gamma = 1$ **AND** $x_\delta = 1$ **then**

 Flip the vectors \vec{X}_γ and \vec{X}_δ .

end if

end if

Output the encoding result.

Preprocessing: We choose the reevaluated bits to be x_5 and x_{15} . We also determine that the parity bits x_1 and x_3 are affected by x_5 alone and the parity bits x_{11}, x_9, x_4 are affected by x_{15} alone. Further, we determine that the parity bit x_2 is affected by both x_5 and x_{15} .

Encoding:

- Step 1. Assign $x_5 = 0$ and $x_{15} = 0$. Encode the pseudo-tree part following the procedures in Section IV.
- Step 2. Compute the values of the parity-check equations C_8 and C_9 , e.g., $\tilde{C}_8 = x_1 \oplus x_2 \oplus x_3 \oplus x_4$ and $\tilde{C}_9 = x_1 \oplus x_2 \oplus x_8 \oplus x_{16}$.
- Step 3a. If $\tilde{C}_8 = 0$ and $\tilde{C}_9 = 0$, stop encoding and output the codeword $[x_1 \ x_2 \ \dots \ x_{16}]$.
- Step 3b. If $\tilde{C}_8 = 1$ and/or $\tilde{C}_9 = 1$, recompute the values of x_5 and x_{15} as the following: $x_5 = \tilde{C}_8$ and $x_{15} = \tilde{C}_9$ where \tilde{C}_8 and \tilde{C}_9 are the values of the parity-check equations C_8 and C_9 , respectively. If $x_5 = 1$ and $x_{15} = 0$, flip the values of the vectors $[x_1 \ x_3]$ and $[x_2]$ to be $[\sim x_1 \ \sim x_3]$ and $[\sim x_2]$, respectively. If $x_5 = 0$ and $x_{15} = 1$, flip the values of the vectors $[x_{11} \ x_9 \ x_4]$ and $[x_2]$ to be $[\sim x_{11} \ \sim x_9 \ \sim x_4]$ and $[\sim x_2]$, respectively. If $x_5 = 1$ and $x_{15} = 1$, flip the values of the vectors $[x_1 \ x_3]$ and $[x_{11} \ x_9 \ x_4]$ to be $[\sim x_1 \ \sim x_3]$ and $[\sim x_{11} \ \sim x_9 \ \sim x_4]$, respectively. Output the codeword $[x_1 \ x_2 \ \dots \ x_{16}]$.

It is easy to revise Algorithm 5 and Algorithm 6 to encode a onefold-constraint encoding stopping set. For example, Algorithm 7 shows the label-decide-recompute algorithm for a onefold-constraint encoding stopping set. The encoding complexity of Algorithm 7 is less than $2 \cdot M \cdot (\bar{k} - 1)$ where M is the number of check nodes in the encoding stopping set and \bar{k} is the average number of bit nodes involved in each check node in the encoding stopping set.

Algorithm 7 Label-decide-recompute algorithm for a onefold-constraint encoding stopping set \mathcal{E}_f with key check node C^* . \mathcal{E}_f contains M check nodes.

Preprocessing (carry out only once):

Use Algorithm 11 to pick an information bit x^* that affects the key parity-check equation C^* .

Use Algorithm 4 to determine the parity bits $x_{p_1}, x_{p_2}, \dots, x_{p_s}$ that are affected by x^* .

Encoding:

Fill the values of the information bits except for x^* .

Assign $x^* = 0$.

Encode $\mathcal{E}_f \setminus C^*$ using Algorithm 2, compute the values of the $M - 1$ parity bits.

Verify the parity-check equation C^* .

if the parity-check equation C^* is not satisfied **then**

$x^* \leftarrow 1$.

for $i = 1$ to s **do**

 Recompute the value of the parity bit x_{p_i} based on the new value of x^* ;

end for

end if

Output the encoding result.

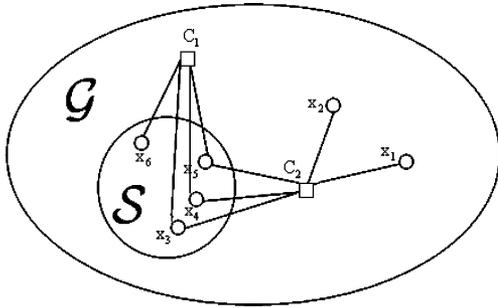


Fig. 7. Outsider nodes.

VII. LINEAR COMPLEXITY ENCODING FOR GENERAL LDPC CODES

In this section, we propose a linear complexity encoding method for general LDPC codes. We will show that any Tanner graph can be decomposed into pseudo-trees and encoding stopping sets that are onefold-constraint or twofold-constraint. By encoding each pseudo-tree or encoding stopping set using Algorithm 2, Algorithm 5, or Algorithm 7, we achieve linear time encoding for arbitrary LDPC codes.

To proceed, we provide the following definition. Given a Tanner graph \mathcal{G} and its subgraph \mathcal{S} , we call the bit nodes in \mathcal{G} but not in \mathcal{S} the *outsider nodes* of \mathcal{S} . For example, Fig. 7 shows a Tanner graph \mathcal{G} and its subgraph \mathcal{S} . Since in Fig. 7 the two bit nodes x_1 and x_2 are in \mathcal{G} but not in \mathcal{S} , x_1 and x_2 are outsider nodes of \mathcal{S} . The check node C_2 involves two outsider nodes of \mathcal{S} , i.e., is connected to two outsider nodes. The check node C_1 involves zero outsider nodes of \mathcal{S} .

We start from LDPC codes with maximum column weight 3 by proving the following lemma.

Lemma 3: Assume the maximum bit node degree of a Tanner graph \mathcal{G} is three, then one of the following statements must be true.

- (E1) There are no pseudo-encoding stopping sets or encoding stopping sets in \mathcal{G} .
- (E2) There exists a pseudo-encoding stopping set in \mathcal{G} . All the bit nodes in the pseudo-encoding stopping set have uniform degree 2.
- (E3) There exists a onefold-constraint or a twofold-constraint encoding stopping set in \mathcal{G} . The key check nodes for the encoding stopping set are specified.

Proof: We only need to prove either condition (E2), or condition (E3), is true if \mathcal{G} contains a pseudo-encoding stopping set, or an encoding stopping set, respectively. We prove this statement by constructing a subgraph \mathcal{S} from the Tanner graph \mathcal{G} . Initially \mathcal{S} is empty. We pick a check node C_1 from \mathcal{G} that involves the smallest number of bit nodes. Next, we add C_1 and all the bit nodes involved in C_1 to \mathcal{S} . We keep adding check nodes and all their associated bit nodes to \mathcal{S} till \mathcal{S} contains a pseudo-encoding stopping set or an encoding stopping set. Each time we add a check node to \mathcal{S} , we always pick the check node that involves the fewest outsider nodes of \mathcal{S} . If \mathcal{S} contains an encoding stopping set, we also add all the check nodes in $\mathcal{G} \setminus \mathcal{S}$ that involves zero outsider nodes to \mathcal{S} . Next, we discuss two different cases.

\mathcal{S} contains an encoding stopping set. Assume \mathcal{S} contains k check nodes and the j th added check node C_j is the last check node that introduces outsider nodes to \mathcal{S} . We will show that $k - j \leq 2$. Assume C_j adds p outsider nodes $x_{j_1}, x_{j_2}, \dots, x_{j_p}$ to \mathcal{S} . We will prove that the $(j + 1)$ th added check node C_{j+1} connects to all the p bit nodes $x_{j_1}, x_{j_2}, \dots, x_{j_p}$. If C_{j+1} does not connect to all the p bit nodes, then C_{j+1} involves a smaller number of outsider nodes than C_j does and should be added earlier than C_j since we always pick the check node that involves the smallest number of outsider nodes and add it first to \mathcal{S} . This contradicts the fact that C_{j+1} is added to \mathcal{S} after C_j . Therefore, C_{j+1} should connect to all the p bit nodes $x_{j_1}, x_{j_2}, \dots, x_{j_p}$. Similarly, C_{j+2}, \dots, C_k connect to all the p bit nodes $x_{j_1}, x_{j_2}, \dots, x_{j_p}$. Since any bit node can connect to at most three check nodes, it follows that $k - j \leq 2$, which means at most two check nodes are added to \mathcal{S} after C_j . Further, we can prove that \mathcal{S} does not contain any encoding stopping set before adding C_{j+1} . The corresponding proof is shown in Appendix C. Hence, the encoding stopping set in \mathcal{S} is either a onefold-constraint encoding stopping set or a twofold-constraint encoding stopping set. The last added $k - j$ check nodes C_{j+1}, \dots, C_k are key check nodes for the constructed onefold-constraint or twofold-constraint encoding stopping set. Condition (E3) is satisfied.

\mathcal{S} is a pseudo-encoding stopping set. It follows that the binary sum of all the check nodes in \mathcal{S} is zero. So, the degree of every bit node in \mathcal{S} is an even number. Since the maximum bit node degree is three, the degree of each bit node in \mathcal{S} is two. Condition (E2) is satisfied.

This completes the proof. \square

We detail the method of determining a pseudo-encoding stopping set or an encoding stopping set in Algorithm 8.

Algorithm 8 Find a pseudo-encoding stopping set or an encoding stopping set (onefold-constraint or twofold-constraint) from a Tanner graph \mathcal{G} with maximum bit node degree 3.

```

 $\mathcal{S} = \phi.$ 
Flag  $\leftarrow$  0.
 $i = 1.$ 
while Flag = 0 and  $\mathcal{G} \neq \mathcal{S}$  do
    Find a check node  $C_i$  in  $\mathcal{G} \setminus \mathcal{S}$  that involves the smallest
    number of outsider nodes of  $\mathcal{S}$ .
    Add  $C_i$  and all its associated outsider nodes to  $\mathcal{S}$ .
    if  $C_i$  does not introduce new bit nodes to  $\mathcal{S}$  then
         $\mathcal{A} \leftarrow \mathcal{S}$ .
        while there exists a bit node  $x$  of degree one in  $\mathcal{A}$ 
            Delete the degree-one bit node  $x$  and the check
            node connecting to  $x$  from  $\mathcal{A}$ .
        end while
        if  $\mathcal{A} = \phi$  then
             $\mathcal{S}$  does not contain any pseudo encoding stopping
            set or encoding stopping set.
        else
            Flag  $\leftarrow$  1.
        end if
    end if
     $i = i + 1.$ 
end while
    
```

```

if Flag = 1 then
  if all the bit nodes in  $\mathcal{A}$  are of degree 2 then
    The subgraph  $\mathcal{A}$  is a pseudo encoding stopping set.
  else
    The subgraph  $\mathcal{A}$  is an encoding stopping set.
  end if
  Output  $\mathcal{A}$ .
else
  The Tanner graph  $\mathcal{G}$  does not contain pseudo-encoding
  stopping sets or encoding stopping sets.
end if

```

Next, we present our main theorem.

Theorem 3: Let \mathcal{G} be the Tanner graph of an LDPC code. If the maximum bit node degree of \mathcal{G} is three, then the LDPC code can be encoded in linear time and the encoding complexity is less than $2 \cdot M \cdot (\bar{k} - 1)$ where M is the number of independent check nodes in \mathcal{G} and \bar{k} is the average number of bit nodes involved in each check node.

Proof: If the Tanner graph \mathcal{G} does not contain any encoding stopping set, then the corresponding LDPC code can be encoded in linear time by Theorem 2. Therefore, we only need to prove Theorem 3 for the case that \mathcal{G} contains encoding stopping sets. Since the maximum bit node degree of \mathcal{G} is three, by Lemma 3 there exists a pseudo-encoding stopping set or an encoding stopping set \mathcal{G}_1 in \mathcal{G} . If \mathcal{G}_1 is a pseudo-encoding stopping set, we simply delete a redundant check node from \mathcal{G}_1 and \mathcal{G}_1 becomes a pseudo-tree. If \mathcal{G}_1 is an encoding stopping set, it is either a one-fold-constraint or a twofold-constraint encoding stopping set by Lemma 3.

Next, we look at the subgraph $\mathcal{G} \setminus \mathcal{G}_1$. We first transform the parity-check equations in $\mathcal{G} \setminus \mathcal{G}_1$ into generalized parity-check equations by moving the bits contained in \mathcal{G}_1 from the left-hand side of the equation to the right-hand side of the equation. Let a parity-check equation C involves k bit nodes x_1, x_2, \dots, x_k where the bits x_{q+1}, \dots, x_k are also in \mathcal{G}_1 , then the parity-check equation $C : x_1 \oplus x_2 \oplus \dots \oplus x_k = 0$ can be rewritten as

$$x_1 \oplus x_2 \oplus \dots \oplus x_q = x_{q+1} \oplus x_{q+2} \oplus \dots \oplus x_k = b. \quad (12)$$

In (12), the parameter b becomes a constant after we encode \mathcal{G}_1 and get the values of all the bits in \mathcal{G}_1 . Since the maximum bit node degree of $\mathcal{G} \setminus \mathcal{G}_1$ is less than or equal to three, we, again, find a pseudo-encoding stopping set or an encoding stopping set \mathcal{G}_2 from $\mathcal{G} \setminus \mathcal{G}_1$. If \mathcal{G}_2 is an encoding stopping set, \mathcal{G}_2 is either a onefold-constraint or a twofold-constraint encoding stopping set by Lemma 3. If \mathcal{G}_2 is a pseudo-encoding stopping set and we assume \mathcal{G}_2 contains the following m generalized parity-check equations:

$$\begin{array}{ccccccc} x_{1,1} & \oplus & x_{1,2} & \oplus & \dots & x_{1,a_1} & = & b_1 \\ x_{2,1} & \oplus & x_{2,2} & \oplus & \dots & x_{2,a_2} & = & b_2 \\ \vdots & & \vdots & & & \vdots & & \vdots \\ x_{m,1} & \oplus & x_{m,2} & \oplus & \dots & x_{m,a_m} & = & b_m \end{array} \quad (13)$$

we derive that

$$b_1 \oplus b_2 \oplus \dots \oplus b_m = 0. \quad (14)$$

Hence, we can replace any generalized parity-check equation in (13) by the new parity check (14). From the above analysis, we can delete any check node from \mathcal{G}_2 to make \mathcal{G}_2 a pseudo-tree if \mathcal{G}_2 is a pseudo-encoding stopping set. To maintain the code structure, we also generate a new check node C^* that represents the parity check (14). Since the parity check (14) only involves bits in \mathcal{G}_1 , we add the new check node C^* to \mathcal{G}_1 and regenerate encoding stopping sets or pseudo-trees in the graph $\mathcal{G}_1 \cup C^*$.

Generally, we can find a pseudo-encoding stopping set or an encoding stopping set \mathcal{G}_{i+1} from the subgraph $\mathcal{G} \setminus \{\mathcal{G}_1 \cup \mathcal{G}_2 \cup \dots \cup \mathcal{G}_i\}$. If \mathcal{G}_{i+1} is an encoding stopping set, \mathcal{G}_{i+1} is either a one-fold-constraint or a twofold-constraint encoding stopping set by Lemma 3. If \mathcal{G}_{i+1} is a pseudo-encoding stopping set, we operate in three steps. In the first step, we sum up all the generalized parity-check equations in \mathcal{G}_{i+1} to generate a new parity-check equation C^* . In the second step, we delete one check node from \mathcal{G}_{i+1} to make \mathcal{G}_{i+1} a pseudo-tree. In the third step, we add the new check node C^* to \mathcal{G}_i and regenerate pseudo-tree or encoding stopping sets in $\mathcal{G}_i \cup C^*$. Notice that the new parity-check equation C^* in (14) does not incur extra cost to compute variables b_1, b_2, \dots, b_m since these variables have already been computed in those generalized parity-check equations in \mathcal{G}_{i+1} , as shown in (13). Practically, we can compute these variables b_1, b_2, \dots, b_m only once and store them. Later, we can apply the stored values b_1, b_2, \dots, b_m to both (14) and (13). Hence, the new parity-check equation C^* only needs $m - 1$ additional XOR operations to compute the summation of b_1, b_2, \dots, b_m . Since the cost of encoding the pseudo-tree \mathcal{G}_{i+1} is $(m - 1) \cdot (\bar{k} - 2)$ where \bar{k} is the average degree of the remaining $m - 1$ check nodes in \mathcal{G}_{i+1} , the overall cost of encoding \mathcal{G}_{i+1} and the new parity-check equation C^* is $(m - 1) \cdot (\bar{k} - 1)$.

By continuing to find pseudo-tree or encoding stopping sets in this way, we reach the stage where $\mathcal{G} \setminus \{\mathcal{G}_1 \cup \mathcal{G}_2 \cup \dots \cup \mathcal{G}_i\} = \phi$ or $\mathcal{G} \setminus \{\mathcal{G}_1 \cup \mathcal{G}_2 \cup \dots \cup \mathcal{G}_i\}$ does not contain pseudo-encoding stopping sets or encoding stopping sets.

By the above analysis, we decompose the Tanner graph \mathcal{G} into a sequence of p subgraphs $\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_p$ where $\mathcal{G}_i, 1 \leq i \leq p$, is either a onefold-constraint encoding stopping set, a twofold-constraint encoding stopping set, or a pseudo-tree. If \mathcal{G}_i is a onefold-constraint or a twofold-constraint encoding stopping set, the key check nodes for \mathcal{G}_i are specified by Lemma 3. Therefore, we apply Algorithm 7 or Algorithm 5 to encode \mathcal{G}_i and the resulting encoding complexity is less than $2 \cdot M_i \cdot (\bar{k}_i - 1)$ where M_i denotes the number of independent check nodes in \mathcal{G}_i and \bar{k}_i denotes the average number of bit nodes involved in each check node in \mathcal{G}_i . If \mathcal{G}_i is a pseudo-tree, we apply Algorithm 1 to encode \mathcal{G}_i and the corresponding encoding complexity is less than $M_i \cdot (\bar{k}_i - 1)$. The overall computation complexity of encoding \mathcal{G} is linear on the number of independent check nodes M in \mathcal{G} and is bounded by $\sum_{i=1}^p (2 \cdot M_i \cdot (\bar{k}_i - 1)) = 2 \cdot M \cdot (\bar{k} - 1)$, where \bar{k} denotes the average number of bits involved in each independent check node of \mathcal{G} . This completes the proof. \square

We summarize the algorithm of decomposing a Tanner graph with maximum bit node degree 3 into pseudo-trees and encoding stopping sets in Algorithm 9 and the algorithm to encode such LDPC codes in Algorithm 10.

Algorithm 9 Decompose a Tanner graph \mathcal{G} with maximum bit node degree 3 into onefold-constraint encoding stopping sets, twofold-constraint encoding stopping sets, and pseudo-trees.

Find a pseudo-encoding stopping set or an encoding stopping set \mathcal{G}_1 from \mathcal{G} using Algorithm 8.
 $\mathcal{G} = \mathcal{G} \setminus \mathcal{G}_1$.
if \mathcal{G}_1 is a pseudo-encoding stopping set **then**
 Delete a check node in \mathcal{G}_1 . \mathcal{G}_1 becomes a pseudo-tree.
end if
 $i = 1$.
while there exists a pseudo-encoding stopping set or an encoding stopping set in \mathcal{G} **do**
 Find a pseudo-encoding stopping set or an encoding stopping set \mathcal{G}_{i+1} from \mathcal{G} using Algorithm 8. Assume \mathcal{G}_{i+1} contain m check nodes C_1, C_2, \dots, C_m .
 $\mathcal{G} = \mathcal{G} \setminus \mathcal{G}_{i+1}$
if \mathcal{G}_{i+1} is a pseudo-encoding stopping set **then**
 $\mathcal{G}_{i+1} = \mathcal{G}_{i+1} \setminus C_m$. \mathcal{G}_{i+1} becomes a pseudo-tree.
 Generate a new check node $C^* = C_1 \oplus C_2 \oplus \dots \oplus C_m$.
 Add C^* to \mathcal{G}_i and regenerate pseudo-trees and encoding stopping sets in $\mathcal{G}_i \cup C^*$.
end if
 $i = i + 1$.
end while
 $\mathcal{G}_{i+1} = \mathcal{G}$.
 Output a sequence of subgraphs $\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_p$ where \mathcal{G}_i , $1 \leq i \leq p$, is either a pseudo-tree or an encoding stopping set (onefold-constraint or twofold-constraint).

Algorithm 10 Linear complexity encoding algorithm for LDPC codes with maximum bit node degree 3

Preprocessing (carry out only once):

Apply Algorithm 9 to decompose the Tanner graph \mathcal{G} of the code into p subgraphs $\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_p$ where \mathcal{G}_i , $i = 1, 2, \dots, p$, is either a pseudo-tree or a onefold-constraint encoding stopping set or a twofold-constraint encoding stopping set with the key check nodes being specified.

Encoding:

for $i = 1$ to p **do**

Compute the constants on the right-hand side of the generalized parity-check equations of \mathcal{G}_i based on the already known bit values of $\mathcal{G}_1, \mathcal{G}_2, \dots, \mathcal{G}_{i-1}$.

if \mathcal{G}_i is a pseudo-tree **then**

Encode \mathcal{G}_i using Algorithm 1.

else

if \mathcal{G}_i is a onefold-constraint encoding stopping set **then**

Encode \mathcal{G}_i using Algorithm 7.

else

Encode \mathcal{G}_i using Algorithm 5.

end if

end if

end for

Output the encoded codeword.

Next, we extend the linear time encoding method described in Theorem 3 to LDPC codes with arbitrary column weight and row weight.

Theorem 4: Any LDPC code \mathcal{C} with arbitrary column weight distribution and row weight distribution can be encoded in linear time, and the corresponding encoding complexity is less than $4 \cdot M \cdot (\bar{k} - 1)$ where M is the number of independent check nodes in \mathcal{C} and \bar{k} is the average degree of check nodes.

Proof: We first show that an LDPC code with arbitrary column weight distribution and row weight distribution can be equivalently transformed into an LDPC code with maximum column weight three. For example, Fig. 8 on the top shows a bit node x of degree 4. It can be split into two bit nodes x and x' of degree 3 and an auxiliary check node C' , as shown on the bottom in Fig. 8. The auxiliary check node C' is represented as $x \oplus x' = 0$, which means x is equivalent to x' . Originally, the bit node x connects to four check nodes C_1, C_2, C_3 , and C_4 . After node splitting, x' connects to C_1, C_2 , and x connects to C_3, C_4 . Hence, the Tanner graph on the top in Fig. 8 is equivalent to the Tanner graph on the bottom in Fig. 8. Similarly, a bit node of degree 5 can be split into three bit nodes x, x' , and x'' and two auxiliary check nodes C' and C'' , as shown in Fig. 9. Generally, a bit node of degree k can be equivalently transformed into $k-2$ bit nodes of degree 3 and $k-3$ auxiliary check nodes, as shown in Fig. 10. Assume an LDPC code \mathcal{C} contains M check nodes and N bit nodes. The M check nodes have degrees k_1, k_2, \dots, k_M , respectively. The N bit nodes have degrees j_1, j_2, \dots, j_N , respectively. Among the N bit nodes in \mathcal{C} , there are s bit nodes whose degrees are greater than 3 and their degrees are j_1, j_2, \dots, j_s . This LDPC code can be equivalently transformed into another LDPC code \mathcal{C}' with maximum column weight 3. The new code \mathcal{C}' has $M + (\sum_{i=1}^s j_i - 3s)$ check nodes and $N + (\sum_{i=1}^s j_i - 3s)$ bit nodes. By Theorem 3, the LDPC code \mathcal{C}' can be encoded in linear time and the encoding complexity is less than $2 \cdot M' \cdot (\bar{k}' - 1)$, where M' is the number of independent check nodes in \mathcal{C}' and \bar{k}' is the average degree of independent check nodes in \mathcal{C}' . Since there are $\sum_{i=1}^s j_i - 3s$ auxiliary check nodes in \mathcal{C}' that have degree 2, we derive that

$$\begin{aligned}
 & 2 \cdot M' \cdot (\bar{k}' - 1) \\
 &= 2 \cdot \left(M \cdot (\bar{k} - 1) + \left(\sum_{i=1}^s j_i - 3s \right) \cdot (2 - 1) \right) \\
 &< 2 \cdot \left(M \cdot (\bar{k} - 1) + \left(\sum_{i=1}^N j_i - N \right) \right) \\
 &< 2 \cdot \left(M \cdot (\bar{k} - 1) + \left(\sum_{i=1}^M k_i - M \right) \right) \\
 &= 4 \cdot M \cdot (\bar{k} - 1)
 \end{aligned} \tag{15}$$

Therefore, the overall computation cost of encoding \mathcal{C}' is less than $4 \cdot M \cdot (\bar{k} - 1)$. As the LDPC code \mathcal{C} is equivalent to

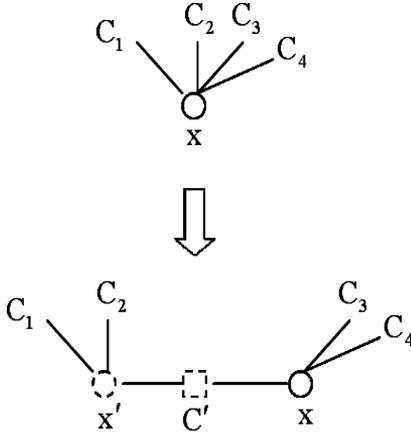


Fig. 8. Transform a bit node of degree 4 into two bit nodes of degree 3 and an auxiliary check node of degree 2.

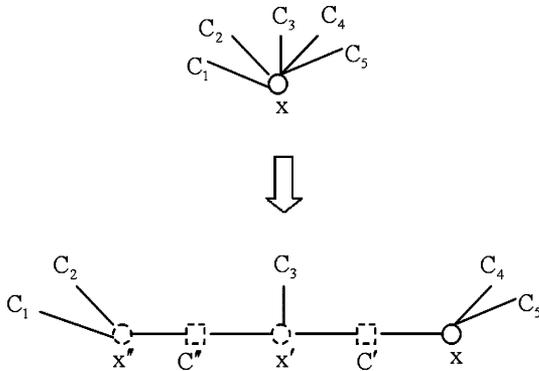


Fig. 9. Transform a bit node of degree 5 into three bit nodes of degree 3 and two auxiliary check nodes of degree 2.

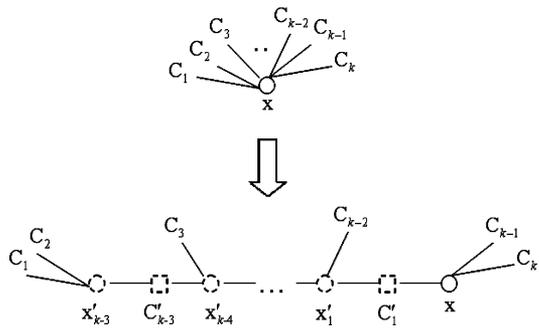


Fig. 10. Transform a bit node of degree k into $k - 2$ bit nodes of degree 3 and $k - 3$ auxiliary check nodes of degree 2.

the LDPC code \mathcal{C}' , the complexity of encoding \mathcal{C} is less than $4 \cdot M \cdot (\bar{k} - 1)$. This completes the proof. \square

Let us look at an example. The parity-check matrix of a $(13, 26)$ LDPC code with column weight 3 is shown in Fig. 11. Assume the values of the 13 information bits are 0, 1, 1, 1, 0, 1, 1, 0, 0, 1, 0, 1, and 1. We apply the proposed linear complexity encoding method to encode this code.

Preprocessing. We construct an encoding stopping set from the LDPC code shown in Fig. 11 using Algorithm 8. We start from an empty graph \mathcal{S} and add check nodes and their associated bit nodes to \mathcal{S} . Each time we add a check node, we always pick

the check node that involves the smallest number of outsider nodes of \mathcal{S} . After adding seven check nodes, the resulting graph is a pseudo-tree, as shown in Fig. 12. When nine check nodes are considered, we get the twofold-constraint encoding stopping set \mathcal{E}_1 with key check nodes C_{10} and C_{12} shown in Fig. 13. The bits $x_9, x_{13}, x_{22}, x_{23}, x_5, x_{16}, x_4, x_{12}, x_{17}$ are information bits. The two bit nodes x_1 and x_{18} are chosen to be reevaluated bits by Algorithm 11.

After finding the encoding stopping set \mathcal{E}_1 , the remaining Tanner graph of the code can be constructed to be a twofold-constraint encoding stopping set \mathcal{E}_2 with key check nodes C_3 and C_5 , as shown in Fig. 14. Therefore, the LDPC code can be partitioned into two encoding stopping sets \mathcal{E}_1 and \mathcal{E}_2 that are shown in Fig. 14. The bits $x_{11}, x_{15}, x_{19}, x_{25}$ in the encoding stopping set \mathcal{E}_2 are information bits. The two bit nodes x_3 and x_6 are chosen to be reevaluated bits of \mathcal{E}_2 by Algorithm 11.

Encoding.

Encode \mathcal{E}_1 :

- Step 1. Fill the values of the information bits, i.e., $[x_9 \ x_{13} \ x_{22} \ x_{23} \ x_5 \ x_{16} \ x_4 \ x_{12} \ x_{17}] = [0 \ 1 \ 1 \ 1 \ 0 \ 1 \ 1 \ 0 \ 0]$. Assign $x_1 = 0$ and $x_{18} = 0$.
- Step 2. Encode the pseudo-tree shown in Fig. 12. Compute the parity bits $x_{21}, x_{14}, x_8, x_7, x_{10}, x_{24}, x_2$ as follows:

$$\begin{aligned} xsx_{21} &= x_1 \oplus x_9 \oplus x_{13} \oplus x_{22} \oplus x_{23} = 1 \\ x_{14} &= x_9 \oplus x_{13} \oplus x_5 \oplus x_{16} \oplus x_{18} = 0 \\ x_8 &= x_{23} \oplus x_{16} \oplus x_{18} \oplus x_4 \oplus x_{12} = 1 \\ x_7 &= x_{13} \oplus x_{23} \oplus x_5 \oplus x_{12} \oplus x_{17} = 0 \\ x_{10} &= x_1 \oplus x_{22} \oplus x_5 \oplus x_4 \oplus x_{17} = 0 \\ x_{24} &= x_{21} \oplus x_{14} \oplus x_8 \oplus x_7 \oplus x_{10} = 0 \\ x_2 &= x_{22} \oplus x_{24} \oplus x_{16} \oplus x_7 \oplus x_4 = 1. \end{aligned}$$

- Step 3. Compute the values of the key parity-check equations C_{10} and C_{12} . $\widetilde{C}_{10} = x_2 \oplus x_9 \oplus x_{10} \oplus x_{12} \oplus x_{14} \oplus x_{18} = 1$, and $\widetilde{C}_{12} = x_1 \oplus x_2 \oplus x_8 \oplus x_{17} \oplus x_{21} = 1$.
- Step 4. Since $\widetilde{C}_{10} = 1$ and $\widetilde{C}_{12} = 1$, the correct values of the reevaluated bits x_1 and x_{18} are $x_1 = \widetilde{C}_{10} = 1$ and $x_{18} = \widetilde{C}_{12} = 1$.
- Step 5. Recompute the parity bits x_{21}, x_{14}, x_8 , and x_{10} based on the new values of x_1 and x_{18} . We derive that $x_{21} = 0, x_{14} = 1, x_8 = 0, x_{10} = 1$.

Encode \mathcal{E}_2 :

- Step 6. Fill the values of the information bits, i.e., $[x_{11} \ x_{15} \ x_{19} \ x_{25}] = [1 \ 0 \ 1 \ 1]$. Assign $x_3 = 0$ and $x_6 = 0$.
- Step 7. Compute the parity bits x_{20}, x_{26} as follows:

$$\begin{aligned} x_{20} &= x_3 \oplus x_6 \oplus x_{11} \oplus x_{15} \oplus x_{19} = 0 \\ x_{26} &= x_3 \oplus x_6 \oplus x_{11} \oplus x_{19} \oplus x_{25} \oplus x_{24} = 1. \end{aligned}$$

Notice that the value of the parity bit x_{26} is based on the value of the bit x_{24} in \mathcal{E}_1 .

- Step 8. Compute the values of the key parity-check equations C_3 and C_5 . $\widetilde{C}_3 = x_3 \oplus x_{20} \oplus x_{11} \oplus x_{15} \oplus x_{26} \oplus x_{25} = 1$, and $\widetilde{C}_5 = x_6 \oplus x_{20} \oplus x_{15} \oplus x_{19} \oplus x_{26} \oplus x_{25} = 1$.

$$\mathbf{H} = \begin{bmatrix}
 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\
 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 1 \\
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 1 & 1 \\
 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 1 & 1 \\
 0 & 1 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 \\
 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
 1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0
 \end{bmatrix}$$

Fig. 11. The parity-check matrix of a (13, 26) LDPC code.

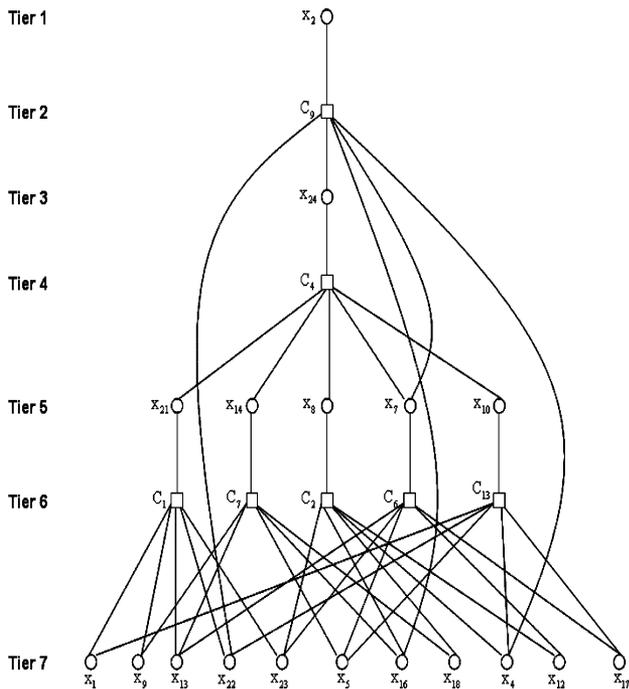


Fig. 12. A pseudo-tree built from the LDPC code described in Fig. 11.

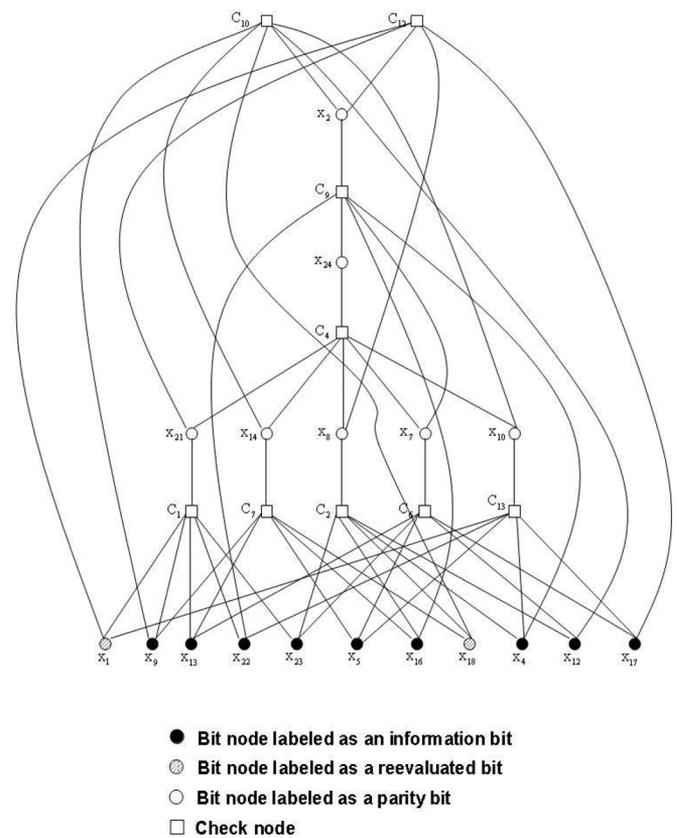


Fig. 13. An encoding stopping set developed from the LDPC code described in Fig. 11.

Step 9. Since $\tilde{C}_3 = 1$ and $\tilde{C}_5 = 1$, the correct values of the reevaluated bits x_3 and x_6 are $x_3 = \tilde{C}_3 = 1$ and $x_6 = \tilde{C}_5 = 1$.

The encoded codeword is $[x_9 \ x_{13} \ x_{22} \ x_{23} \ x_5 \ x_{16} \ x_4 \ x_{12} \ x_{17} \ x_1 \ x_{18} \ x_{21} \ x_{14} \ x_8 \ x_7 \ x_{10} \ x_{24} \ x_2 \ x_{11} \ x_{15} \ x_{19} \ x_{25} \ x_3 \ x_6 \ x_{20} \ x_{26}] = [0 \ 1 \ 1 \ 1 \ 0 \ 1 \ 1 \ 0 \ 0 \ 1 \ 1 \ 0 \ 1 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0 \ 0 \ 1 \ 0 \ 1 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 1 \ 0 \ 1 \ 1]$.

VIII. CONCLUSION

This paper proposes a linear complexity encoding method for general LDPC codes by analyzing and encoding their Tanner graphs. We show that two particular types of Tanner graphs: pseudo-trees and encoding stopping sets can be encoded in

linear time. Then, we prove that any Tanner graph can be decomposed into pseudo-trees and encoding stopping sets. By encoding the pseudo-trees and encoding stopping sets in a sequential order, we achieve linear complexity encoding for arbitrary LDPC codes. The proposed method can be applied to a wide range of codes; it is not limited to LDPC codes. It is applicable to both regular LDPC codes and irregular LDPC

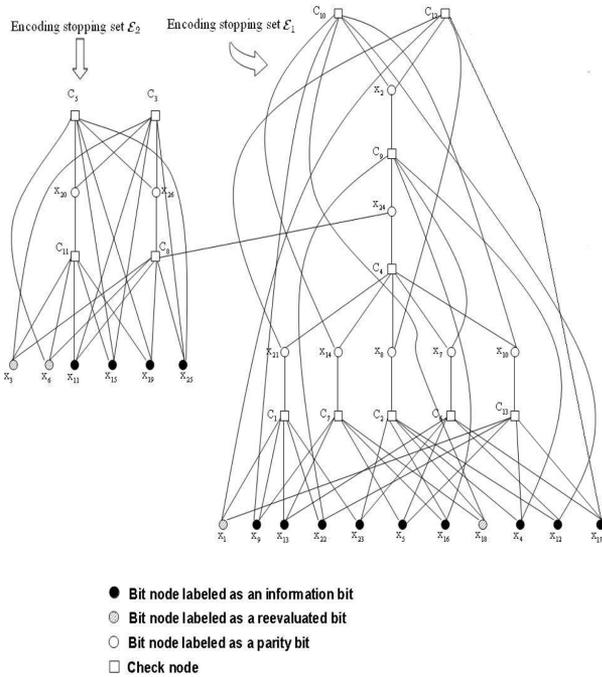


Fig. 14. Two encoding stopping sets developed from the LDPC code described in Fig. 11.

codes. In fact, the proposed linear time encoding method is applicable to any type of block codes. It removes the problem of high encoding complexity for all long block codes that historically are commonly encoded by matrix multiplication.

APPENDIX A PROOF OF LEMMA 2

We prove Lemma 2 by contradiction. Assume a pseudo-tree \mathcal{T} contains an encoding stopping set \mathcal{E}_f . Let C' be an arbitrary check node in the encoding stopping set \mathcal{E}_f and C' is located in the $2i$ th tier of \mathcal{T} . According to condition (B1), all the bit nodes that connect to C' , which include the parent bit node of C' , are also in the encoding stopping set \mathcal{E}_f . By condition (B2), there exists another check node C'' in \mathcal{E}_f that connects to the parent bit node of C' . By condition (A4), the check node C'' must be in a tier above $2i-1$. By the above reasoning, we conclude that the encoding stopping set \mathcal{E}_f must contain a check node above the $2i$ th tier if \mathcal{E}_f contains a check node in the $2i$ th tier. By repeatedly using the above conclusion, we derive that the encoding stopping set \mathcal{E}_f must contain a check node C''' in tier 2. By condition (B1), the parent bit node of C''' , which is in the first tier of \mathcal{T} , is also in the encoding stopping set \mathcal{E}_f . However, by condition (A2), the parent bit node of C''' has degree one, which violates condition (B2) that every bit node in \mathcal{E}_f has degree greater than or equal to two. Therefore, the assumption is wrong. Any pseudo-tree cannot contain an encoding stopping set. Similarly, we can prove that the union of pseudo-trees cannot contain any encoding stopping set. This completes the proof. \square

APPENDIX B

FINDING REEVALUATED BITS x_γ AND x_δ IN A TWOFOLD-CONSTRAINT ENCODING STOPPING SET WITH KEY CHECK NODES C_α AND C_β

The details are described in Algorithm 11.

Algorithm 11 Finding reevaluated bits x_γ and x_δ in a twofold-constraint encoding stopping set with key check nodes C_α and C_β .

Transform the two key check equations C_α and C_β into equivalent parity-check equations C'_α and C'_β that involve only information bits. Assume C'_α involves q information bits $x_{\alpha_1}, x_{\alpha_2}, \dots, x_{\alpha_q}$, and C'_β involves p information bits $x_{\beta_1}, x_{\beta_2}, \dots, x_{\beta_p}$.

$Flag \leftarrow 0$.

for $i = 1$ to q **do**

if x_{α_i} is involved in C'_α but not in C'_β **then**

$Flag \leftarrow 1$.

Choose the reevaluated bit x_γ to be $x_\gamma = x_{\alpha_i}$. Exit the for loop.

end if

end for

if $Flag = 1$ **then**

Choose the reevaluated bit x_δ to be $x_\delta = x_{\beta_p}$.

else

Choose the reevaluated bit x_γ to be $x_\gamma = x_{\alpha_q}$.

for $i = 1$ to p **do**

if x_{β_i} is involved in C'_β but not in C'_α **then**

Choose the reevaluated bit x_δ to be $x_\delta = x_{\beta_i}$. exit the for loop.

end if

end for

end if

Output the two chosen reevaluated bits x_γ and x_δ .

Next, we prove that Algorithm 11 can successfully find two bits x_γ and x_δ that satisfy conditions (D1) to (D3).

Proof: We discuss two different cases.

Algorithm 11 chooses a bit x_γ that is involved in C'_α but not in C'_β . Since the bit x_γ is directly involved in the parity-check equations C'_α and C'_α is equivalent to C_α , the value change of x_γ alone will affect the value of C_α . Hence, condition (D1) is satisfied. Since Algorithm 11 also chooses another bit x_δ that is directly involved in the parity-check equation C'_β and C'_β is equivalent to C_β , the value change of x_δ alone will affect the value of C_β . Hence, condition (D2) is satisfied. Since the parity-check equation C'_β only involves the bit x_δ but not the bit x_γ and C'_β is equivalent to C_β , the value changes of both x_δ and x_γ will change the value of C_β . Hence, condition (D3) is also satisfied.

Algorithm 11 chooses a bit x_γ that is involved in both C'_α and C'_β . Since the bit x_γ is directly involved in the parity-check equations C'_α and C'_α is equivalent to C_α , the value change of x_γ alone will affect the value of C_α . Hence, condition (D1) is satisfied. Since Algorithm 11 also chooses another bit x_δ that is

directly involved in the parity-check equation C'_β but not in C'_α and C'_β is equivalent to C_β , the value change of x_δ alone will affect the value of C_β . Hence, condition (D2) is satisfied. Since the parity-check equation C'_α only involves the bit x_γ but not the bit x_δ and C'_α is equivalent to C_α , the value changes of both x_δ and x_γ will change the value of C_α . Hence, condition (D3) is also satisfied.

This completes the proof. \square

APPENDIX C

IN THE PROOF OF LEMMA 3, THE SUBGRAPH \mathcal{S} DOES NOT CONTAIN ANY ENCODING STOPPING SET BEFORE ADDING A CHECK NODE THAT INVOLVES ZERO OUTSIDER NODES

Proof: We prove this fact by contradiction. Assume the subgraph \mathcal{S} contains an encoding stopping set \mathcal{E}_f before adding a check node that involves zero outsider nodes. Let the encoding stopping set \mathcal{E}_f contain m check nodes $C_1, C_2, \dots, C_{m-1}, C_m$, and the check node C_m is being added to the subgraph \mathcal{S} later than all the other check nodes C_1, C_2, \dots, C_{m-1} in \mathcal{E}_f . From the construction process of \mathcal{S} , all the bit nodes that are involved in check nodes C_1, C_2, \dots, C_{m-1} have already been in \mathcal{S} before the check node C_m is being added to \mathcal{S} . By definition, all the bit nodes that are involved in check nodes C_1, C_2, \dots, C_{m-1} are not outsider nodes when C_m is being added to \mathcal{S} . Further, C_m introduces at least one outsider node x_o to \mathcal{S} . Therefore, the outsider node x_o is not connected to any of the check nodes in the encoding stopping set \mathcal{E}_f except for C_m . Since x_o connects to the check node C_m and C_m is in the encoding stopping set \mathcal{E}_f , x_o is also in \mathcal{E}_f by condition (B1). However, x_o is only connected to the check node C_m in \mathcal{E}_f , which violates condition (B2) that every bit node in an encoding stopping set is connected to at least two check nodes in the encoding stopping set. Hence, the assumption is wrong. The subgraph \mathcal{S} does not contain any encoding stopping set before adding a check node that involves zero outsider nodes. This completes the proof. \square

ACKNOWLEDGMENT

The authors would like to thank the anonymous reviewers for their suggestions which significantly improved the presentation of the results in this paper and to Dr. Igal Sason for his leadership with this paper.

REFERENCES

- [1] R. G. Gallager, *Low-Density Parity Check Codes*. Cambridge, MA: MIT Press, 1963.
- [2] D. J. C. Mackay, "Good error-correcting codes based on very sparse matrices," *IEEE Trans. Inf. Theory*, vol. 45, no. 2, pp. 399–431, Mar. 1999.
- [3] G. Berrou, A. Glavieux, and P. Thitimajshima, "Near Shannon limit error-correcting coding: Turbo codes," in *Proc. 1993 IEEE Int. Conf. Communications*, Geneva, Switzerland, May 1993, pp. 1064–1070.
- [4] J. Lu, J. M. F. Moura, and H. Zhang, "Efficient encoding of cycle codes: A graphical approach," in *Proc. 37th Asilomar Conf. Signals, Systems, and Computers*, Pacific Grove, CA, Nov. 2003, pp. 69–73.

- [5] Z. Li, L. Chen, L. Zeng, S. Lin, and W. H. Fong, "Efficient encoding of quasi-cyclic low-density parity-check codes," *IEEE Trans. Commun.*, vol. 54, no. 1, pp. 71–81, Jan. 2006.
- [6] T. Mittelholzer, "Efficient encoding and minimum distance bounds of Reed-Solomon-type array codes," in *Proc. IEEE Int. Symp. Information theory (ISIT 2002)*, Lausanne, Switzerland, Jun. 2002, p. 282.
- [7] J. Lu and J. M. F. Moura, "TS-LDPC codes: Turbo-structured codes with large girth," *IEEE Trans. Inf. Theory*, vol. 53, no. 3, pp. 1080–1094, Mar. 2007.
- [8] Y. Kou, S. Lin, and M. P. C. Fossorier, "Low-density parity-check codes based on finite geometries: A rediscovery and new results," *IEEE Trans. Inf. Theory*, vol. 47, no. 7, pp. 2711–2736, Nov. 2001.
- [9] S. J. Johnson and S. R. Weller, "A family of irregular LDPC codes with low encoding complexity," *IEEE Commun. Lett.*, vol. 7, no. 2, pp. 79–81, Feb. 2003.
- [10] S. Freundlich, D. Burshtein, and S. Litsyn, "Approximately lower triangular ensembles of LDPC codes with linear encoding complexity," *IEEE Trans. Inf. Theory*, vol. 53, no. 4, pp. 1484–1494, Apr. 2007.
- [11] M. Yang, W. E. Ryan, and Y. Li, "Design of efficiently encodable moderate-length high-rate irregular LDPC codes," *IEEE Trans. Commun.*, vol. 52, no. 4, pp. 564–570, Apr. 2004.
- [12] D. Haley, A. Grant, and J. Buetefer, "Iterative encoding of low-density parity-check codes," in *Proc. IEEE Globecom 2002*, Taipei, Taiwan, ROC, Nov. 2002, vol. 2, pp. 1289–1293.
- [13] D. Haley and A. Grant, "High rate reversible LDPC codes," in *Proc. 5th Australian Communications Theory Workshop*, Newcastle, Australia, Feb. 2004, pp. 114–117.
- [14] T. J. Richardson and R. L. Urbanke, "Efficient encoding of low-density parity-check codes," *IEEE Trans. Inf. Theory*, vol. 47, no. 2, pp. 638–656, Feb. 2001.
- [15] R. M. Tanner, "A recursive approach to low complexity codes," *IEEE Trans. Inf. Theory*, vol. IT-27, no. 5, pp. 533–547, Sep. 1981.
- [16] C. Di, D. Proietti, E. Telatar, T. Richardson, and R. Urbanke, "Finite-length analysis of low-density parity-check codes on the binary erasure channel," *IEEE Trans. Inf. Theory*, vol. 48, no. 6, pp. 1570–1579, Jun. 2002.

Jun Lu (S'01–M'06) received the bachelor and master degrees from Tsinghua University, Beijing, China, and the Ph.D. degree in electrical and computer engineering from Carnegie Mellon University, Pittsburgh, PA, in 2004.

Then he joined Sun Microsystems, Broomfield, CO, as a researcher. His research interests focus on developing and designing structured LDPC codes with large girth, efficient LDPC encoding and decoding algorithms, hardware implementation of LDPC codes, and advanced signal detection and timing recovery schemes for high-density magnetic recording channels. He holds four issued or pending patents.

José M. F. Moura (S'71–M'75–SM'90–F'94) received the engenheiro electrotécnico degree from Instituto Superior Técnico (IST), Lisbon, Portugal, and the M.Sc., E.E., and the D.Sc. degrees in electrical engineering and computer science from the Massachusetts Institute of Technology (MIT), Cambridge.

He is a Professor of Electrical and Computer Engineering and of BioMedical Engineering at Carnegie Mellon University, Pittsburgh, PA, and a founding Codirector of the Center for Sensed Critical Infrastructures Research (Cen-SCIR). During 2006–2007, he is a Visiting Professor of Electrical Engineering at MIT. He was on the faculty at IST (1975–1984) and has held visiting faculty appointments at MIT (1984–1986 and 1999–2000) and as a research scholar at the University of Southern California (USC), Los Angeles (summers of 1978–1981). His research interests include statistical and algebraic signal processing and digital communications, on which he has published extensively and he holds six patents.

Dr. Moura is the President Elect of the IEEE Signal Processing Society (SPS) and was the Editor-in-Chief for the IEEE TRANSACTIONS IN SIGNAL PROCESSING (1975–1999). He has been on the Editorial Board of the PROCEEDINGS OF THE IEEE, the IEEE SIGNAL PROCESSING MAGAZINE, and the *ACM Transactions on Sensor Networks* and on the program committee of numerous Conferences and Workshops. He is a Fellow of the American Association for the Advancement of Science (AAAS), and a corresponding member of the Academy of Sciences of Portugal (Section of Sciences). He was awarded the 2003 IEEE Signal Processing Society meritorious service award and in 2000 the IEEE Millennium Medal. He is affiliated with several IEEE societies, Sigma Xi, AMS, AAAS, IMS, and SIAM.