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Verification, Validation & Certification

Distributed Embedded Systems

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**Carnegie
Mellon**

Where Are We Now?

◆ Where we've been:

- How to build and analyze things
- Testing – but that is only one way to evaluate how well something is built

◆ Where we're going today:

- Validation, Verification & Certification – making sure it works
 - Largely this focuses on the design correctness part of dependability
 - It should also deal with failure modes and safety

◆ Where we're going next:

- Economics
- Test #1
- Embedded networks
- Mid-semester presentations
- Dependable/safe/secure systems

Preview

◆ Three related concepts:

- Verification: making sure each design step does what it was supposed to do
- Validation: making sure the end result satisfies requirements
- Certification: a written guarantee that a system is acceptable for operational use

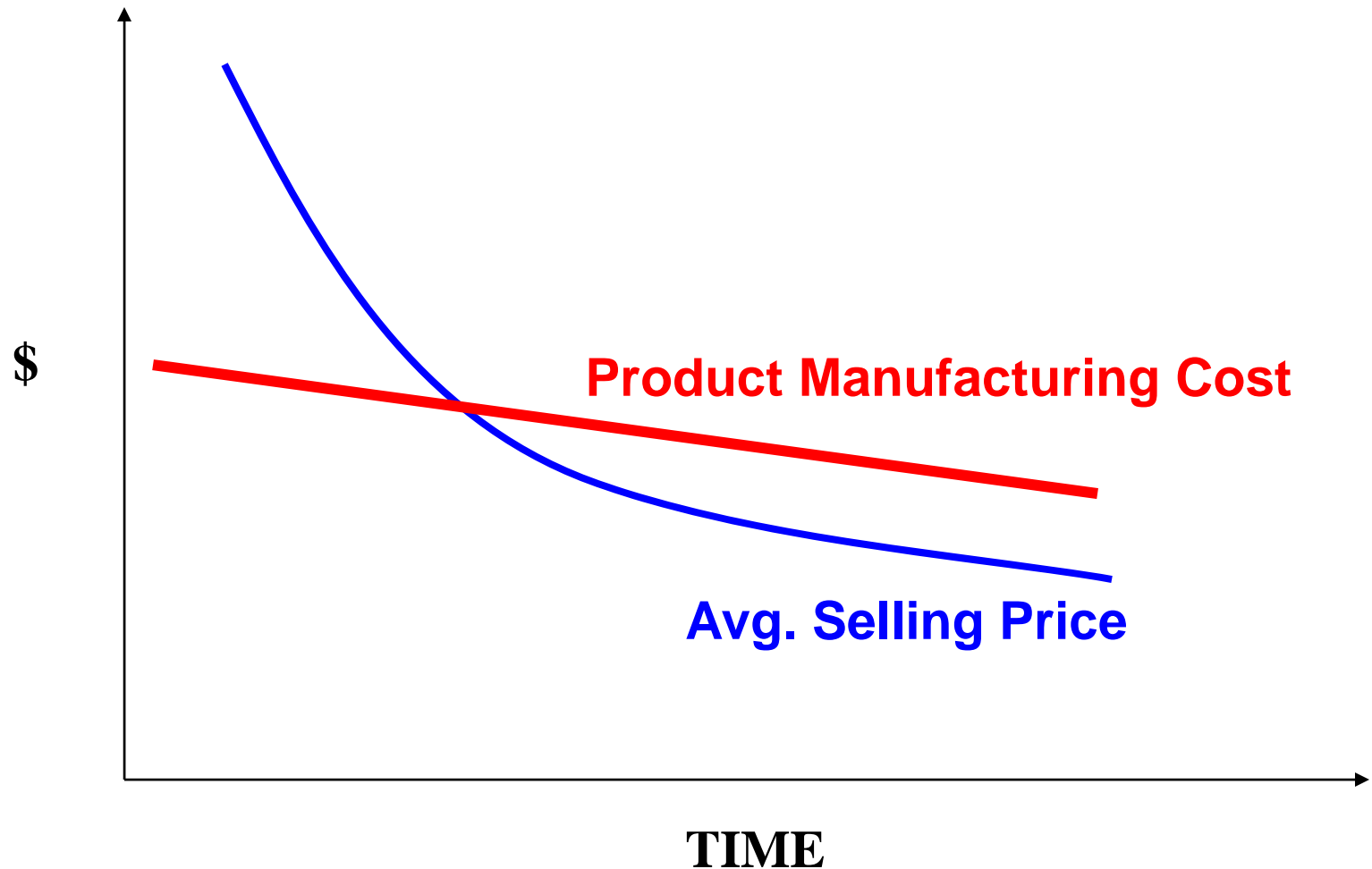
◆ General Approaches

- Testing
- Analysis
- Certification strategies

◆ Areas of concern:

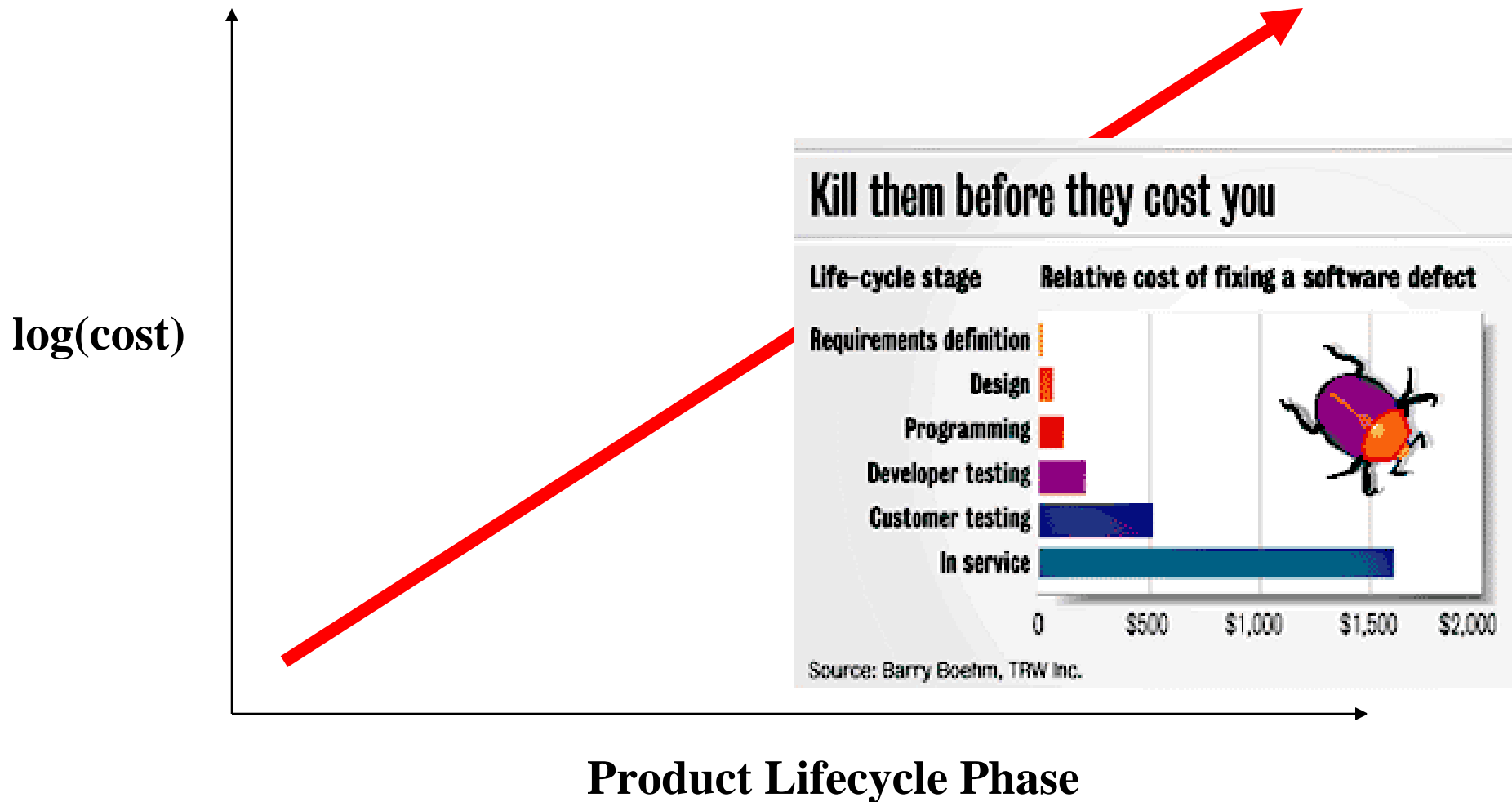
- Hardware correctness
- Software correctness

Why Is Time To Market Important?



- ◆ **Profit window for consumer/commodity electronics may be 3 months**
 - Moral: Get it right the first time; use good process to improve your odds
 - Sometimes – make profits on services/software, not hardware items

What's The Cost Of A Finding & Fixing A Defect?



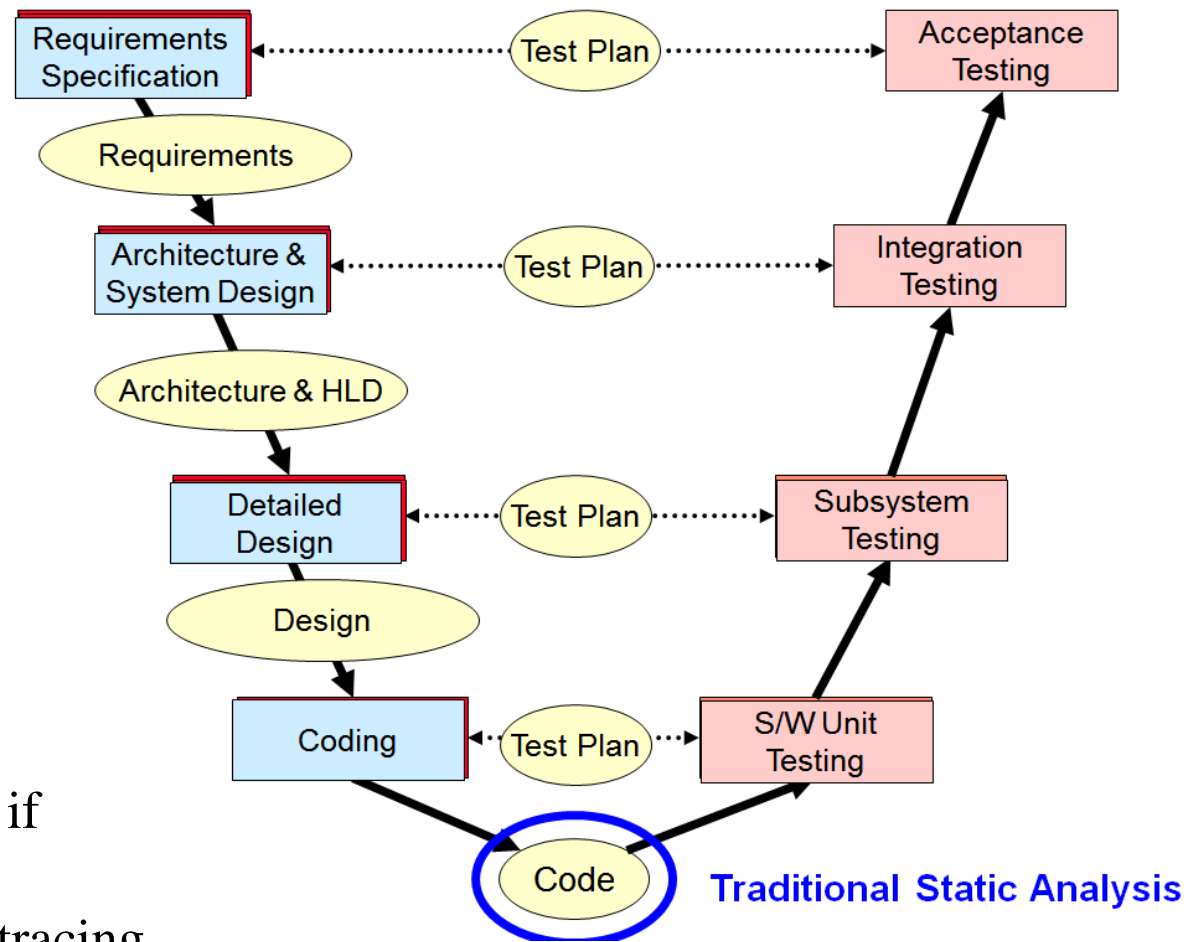
- ◆ Get it right the first time if you can
- ◆ If you get it wrong, find out about it as soon as possible

Is Speed The Key To Success?

- ◆ **A fast design process only helps if you get it right**
 - If you get it wrong, you get to spend more money fixing problems because you move further into the design before you find them!

Traceability

- ◆ **Traceability is checking to ensure steps fit together**
 - Starting point for most V&V
- ◆ **Forward Traceability:**
 - Next step in process has everything in current step
 - “Nothing got left out”
- ◆ **Backward Traceability**
 - Previous step in process provoked current step
 - “Nothing spurious included/no gold plating”
- ◆ **Traceability is an audit**
 - Doesn't prove correctness if tracing is OK
 - But, problems are there if tracing fails



Definitions

◆ Verification:

- The process of evaluating a system or component to determine whether the **products of a given development phase satisfy the conditions imposed** at the start of that phase.
- *Loosely*: forward traceability as design progresses
- **“Did we build the product correctly?”**

◆ Validation:

- The process of evaluating a system or component during or at the end of the development process to determine whether it **satisfies specified requirements**.
- *Loosely*: backward traceability to requirements
- **“Does the product do what it should?”**

◆ Certification:

- A written guarantee that a system or component complies with its specified requirements and is **acceptable for operational use**.
- **“Is an 3rd party happy enough with the product to stake his/her reputation on it?”**

◆ Degree of required V/V/C often set by regulators (e.g., FAA)

General Approaches To V/V/C

◆ Testing

- Execute system to determine behavior
- Inject intentional faults to determine system response

◆ Analysis

- Determine if desirable properties hold true; if undesirable properties exist
- Find inconsistencies among design phases
- Determine if design rules have been followed
- Scrutinize design and documents (reviews)

◆ Process inspection

- Determine if process is appropriate for desired end result
- Determine if process was adequately followed

◆ Many techniques can be used for any of Verif., Valid., Cert.

- But, some techniques are better fits for a particular use

Testing Review/Summary

◆ White-box testing (“structural testing”)

- Look at program structure and design tests
 - e.g., 100% of branch path coverage (both sides of each branch)

◆ Black-box testing (“functional testing”)

- Test every item on the functional specification
- Also, test for robustness/error handling

◆ Levels of test

- Unit test – testing small pieces of code; done by programmer
- Module/functional test – testing at API level; done by testing group
- Integration test – testing pieces working together; done by testing group
- Acceptance test – testing whole system; done by customer (or surrogate)
- Beta test – letting a few customers use product before full production
- Regression test – make sure changes haven’t re-activated old bugs

Starting Points For Embedded Test Coverage

- ◆ **Below are example useful coverage metrics**
 - But remember from testing lectures – 100% coverage is not “100% tested”
- ◆ **Requirements coverage**
 - All requirements tested in every major operating mode
- ◆ **Scenario coverage**
 - All sequence diagrams tested (this is a form of system integration testing)
- ◆ **Statechart coverage**
 - All states visited
 - All arcs exercised
- ◆ **Code coverage**
 - Every statement in program executed (100% branch coverage)
 - Every exception handler exercised; every fault handler exercised
- ◆ **FMEA coverage**
 - FMEA = Failure Mode Effect Analysis (table predicting results of component faults)
 - Inject faults to see if FMEA correctly predicts system response

Things Other Than SW Get Tested Too!

◆ Hardware testing

- “Shake & Bake” testing – temperature and vibration
- STRIFE testing – stress + life – run just beyond hardware limits
 - E.g., 5% over-voltage and 5% over temperature
 - Components that fail are “weak”, and likely to be field failure sources
- Margin testing
 - E.g., increase clock speed until something breaks
 - See if there is enough design margin to account for component variation & aging

◆ System-level testing (“execution” of human use of system)

- Usability tests
- Check that maintenance can be performed within required time limits
- Ensure that install & maintenance procedures work

◆ Software gets stress tested ... but nobody really knows what that means (in any rigorous way)!

Cost To Certify An IEEE 802.16e Aircraft Radio

Environmental Conditions	Category and Requirement	Cost (Euro)
Temperature / Altitude	DO-160E, Section 4, cat.A2	1800
Temperature variation	DO-160E, Section 5, cat. B	1200
Humidity	DO-160E, Section 6, cat. B	5500
Operational shock and crash safety	DO-160E, Section 7, cat B	1700
Vibration	DO-160E, Section 8, curve R	5000
Explosion proofness	DO-160E, Section 9, cat. X	n/a
Waterproofness	DO-160E, Section 10, cat. Y (condensation)	600
Fluid susceptibility	DO-160E, Section 11, cat. F	1700
Sand and dust	DO-160E, Section 12, cat. X (cat X means n/a)	n/a
Fungus resistance	DO-160E, Section 13, cat. F	2000
Salt spray	DO-160E, Section 14, cat. X	n/a
Fire, Flammability	DO-160 E, Section 26, Category C	2000
Magnetic effect	DO-160E, Section 15, cat. Z	1000
Power supply	DO-160E, Section 16, cat. [BZ]	3000
Voltage spike	DO-160E, Section 17, cat. A	1000
Audio frequency conducted susceptibility	DO-160E, Section 18, cat. Z	1000
Induced signal susceptibility	DO-160E, Section 19, cat. Z	2000
Conducted susceptibility	DO-160E, Section 20, cat. W	3000
Radiated susceptibility	DO-160E, Section 20, cat. G 100 to 200 V/m SW/CW and HIRF 700 to 3500 V/m PM	6000
Conducted emission of radio frequency energy	DO-160E, Section 21, cat. H	1000
Radiated emission of radio frequency energy	DO-160E, Section 21, cat. H	2000
Lightning induced transient susceptibility	DO-160E, Section 22 cat A3G33J33	5000
Lightning direct effects	DO-160E, Section 23, cat. X	n/a
Icing	DO-160E, Section 24, cat. X	n/a
Electrostatic discharge	DO-160E, Section 25, cat. A	2000
Bonding	MIL-STD 464, parag. 5	1000
Manufacturer extra effort		(person.day)
Planning, follow-up, investigations, result analysis		140

Source:
Rockwell Collins
1/29/2009

Table 3: DO-160E Qualification Costs

Role Of Testing

◆ Mostly for Validation:

- Unit test – does the unit behave as it should?
- Acceptance test – if customer accepts product, that validates system is OK

◆ Certification

- For narrow certification, can test a specific property
 - FCC certification that system does not emit too much RF interference
- For broader certification, may need tests to give credibility to analyses
 - “Wing snap” test on Boeing 777 was used to demonstrate **stress model accuracy**
 - For X-by-Wire, might need tests to demonstrate models represent actual vehicle

Run-Time Instrumentation

- ◆ **Related idea is to perform some “tests” all the time**
 - Even in production units!
 - Everyday system usage forms the “workload”
 - Use a data recorder to catch and report problems for later analysis

- ◆ **Selected run-time “test” techniques**
 - Log actions and analyze logs
 - Assertions
 - e.g., `#assert RPM < RedLineLimit`
 - Doesn't enforce this – just checks for when it happens
 - Throws an exception if assertion fails at run-time; good for monitoring invariants
 - Monitor system resources, e.g., memory exhaustion
 - Log all exceptions that occur
 - Detect loss of control loop closure
 - Commanded position too far from actual position for an actuator

Error Logs

- ◆ **Keep a run-time log of errors you encounter**
- ◆ **Helps detect bugs that escape into fielded products**
 - A robustly designed system will hide many bugs from the user...
... so how do you know problems are happening?
 - For example, watchdog timer resets
 - For example, running control loops fast to tolerate occasional missed deadline
 - Permits early detection of problems that haven't been seen by customer
 - If a run-time error occurs, something is wrong with your design
 - What to log: system resets, run-time errors, assertion violations, hardware failures, non-computer failures (problems with the plant), operating conditions, time stamps
- ◆ **Protects software developers from blame**
 - “Product is acting weird; must be software”...
... “Our error logs say it is a hardware problem; go harass them instead”

X-by-Wire Fault Injection

- ◆ **Assume that the safety case's fault hypothesis is:**
“Continues to operate despite an arbitrary single point fault”
 - Then, it makes sense to test “arbitrary” faults
 - Hardware or software-based fault injection makes sense

- ◆ **Potential approaches to X-by-Wire fault injection:**
 - Test software that corrupts bits in memory
 - Used successfully in many areas
 - Radiation chamber
 - Used successfully to find problems with TTP
 - Network message fault injection
 - Corrupt or drop messages on network
 - Pin-level fault injection
 - Disturb electrical signals on circuit boards



[TTTech04]

Analysis

- ◆ **Examination of software & documentation**
 - No actual execution of real software
 - Very effective at finding defects in requirements, design, and software
- ◆ **Includes varying levels of tool / human involvement**
 - Ranges from complete static analysis by a compiler-like tool...
 - ... to humans sitting in a conference room looking at requirements documents
- ◆ **Primary techniques we'll discuss:**
 - Traceability
 - Reviews
 - Static analysis
 - Model checking

 - Safety analysis (FTA/FMEA/etc.) –discussed in separate lecture

Refresher On Design Reviews

- ◆ **Design reviews are the most cost-effective way of preventing defects**
 - Think of it as V&V during design instead of after the fact
- ◆ **Simple version:**
 - Explain your software to someone else, going through it line by line
 - Explaining it out loud to yourself is helpful, but not good enough
 - Doing it via e-mail generally isn't good enough –
too easy to sweep things under rug or miss subtleties
- ◆ **More industrial-strength design reviews**
 - Get a book on how to run design reviews
 - Convene a set of people do to a review in a fixed length of time
 - Have people study the code before the review; assign roles to reviewers
 - Have the presenter go through it and answer questions
 - Take corrective action; iterate reviews if necessary
 - Part of this is knowing what to review (checklist is recommended reading); part of it is having someone who knows how to run an effective review

Static Checking & Compiler Warnings

◆ Static analysis looks at design or code to find problems

- E.g., look at statechart for states not connected to any other states
- E.g., look at software for “dead code” – code that can’t be reached by any possible execution path
- Can be done manually, but better to use tools if available

◆ Example static analysis approaches:

- “Lint” / C compiler warning messages (and MISRA C style checkers)
 - Questionable syntax
 - Type checking errors
 - Bad practices
- Tools to compute McCabe Cyclomatic Complexity
 - Simplistically, Cyclomatic Complexity is number of branches in a code module
 - High complexity means code is more failure prone and more difficult to test
- More complex tools, such as finding possible memory leaks and unhandled exceptions
- Always leave warnings turned on and ensure code compiles “clean”
 - This is basically a “free” design review – why would you ignore it???

2012 Coverity scan of open source software results:

◆ Sample size: 68 million lines of open source code

- Control flow issues: 3,464 errors
- Null pointer dereferences: 2,724
- Resource leaks: 2,544
- Integer handling issues: 2,512
- Memory – corruptions : 2,264
- Memory – illegal accesses: 1,693
- Error handling issues: 1,432
- Uninitialized variables: 1,374
- Unintialized members: 918

◆ Notes:

- Warning density 0.69 per 1,000 lines of code
- Most open source tends to be non-critical code
- Many of these projects have previously fixed bugs from previous scans

<http://www.embedded.com/electronics-blogs/break-points/4415338/Coverity-Scan-2012?cid=Newsletter+-+Whats+New+on+Embedded.com>

Model Checking

- ◆ **Model checking is a formal method for verifying finite-state concurrent systems**

- ◆ **Intuitive explanation:**
 - Start with a model of a system. Might be something like a statechart.
 - State an invariant that should apply:
 - E.g., “All network nodes eventually belong to a single group after a single error”
 - E.g., “Motor will not be commanded to run if any elevator doors are open”
 - Run a model checker, which explores all possible transitions through statechart
 - There are, in general, *many* transitions.
 - Model checker says one of two things:
 1. “I’ve looked at all possible execution paths, and what you say is guaranteed true”
 2. “I found a counter-example: here it is...”

(For more explanation, see: <http://www.cs.cmu.edu/~modelcheck/tour.htm>)

Applying Model Checking

- ◆ **Model checking is very good for proving pieces of systems correct**
 - Complexity is exponential with number of states
 - So it doesn't work with arbitrarily large systems; but technology improves yearly
 - OK for aspects of network protocols and small pieces of software

- ◆ **But, there are some cautions:**
 - Tests a model of design, not actual code. Software defects can still occur. Models might have errors, etc.
 - Requires specialized skills; not accessible to everyday engineers yet.
 - Model has underlying assumptions!
 - Assumptions are usually not true in all cases
 - Arguing that an assumption is “reasonable” is insufficient for 10^{-9} failure rates!
 - Scalability is always an issue – can't model check a whole car

 - The tricky part is knowing what properties to check!

Certification



◆ Some Certifying Authority says that it is “good enough”

- Certification of individuals – licensed PE
- Certification of organizations – ISO 9000; CMM Level 3
- Certification of tools/methods – certified Ada compiler
- Certified systems or products – UL-listed

◆ May be process- or product-based

- UL labs – based on standardized tests of products
- ISO 9000 – audit of process
- ... and lots of places in between

◆ Certification may not be a warranty

- Warranty gives legal remedies; certification means it is up to some standard level of “goodness”
- Certification simply places the reputation of the certifier at stake

Example: FAA Software Certification

◆ Based on RTCA/DO-178B

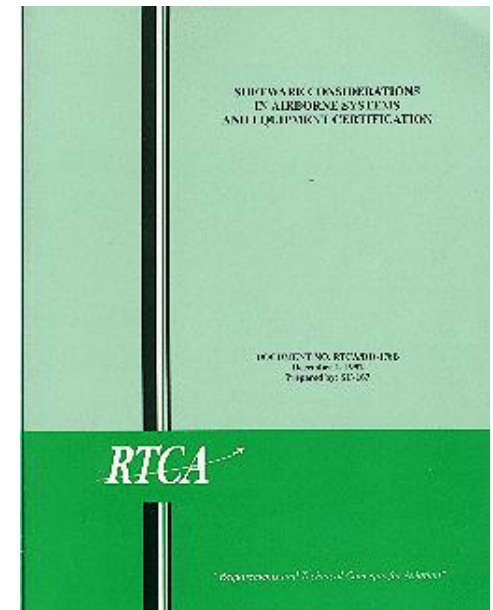
- Demonstrate that it satisfies requirements
- Demonstrate there are no errors leading to catastrophic failure
- (Newer version RTCS/DO-178C is recently out)

◆ Verification:

- HW/SW integration testing
- SW integration testing
- Low-level testing
- Requirements-based test coverage analysis
- Structural coverage analysis

◆ Alternate verification methods

- Formal methods
- Exhaustive input testing



Example: UL 1998 for Software Components

◆ Consumer electronics certification addresses software

- For software that replaces functions that previously had hardware protection
- They want to see the software! Testing alone just isn't good enough

◆ Requirements:

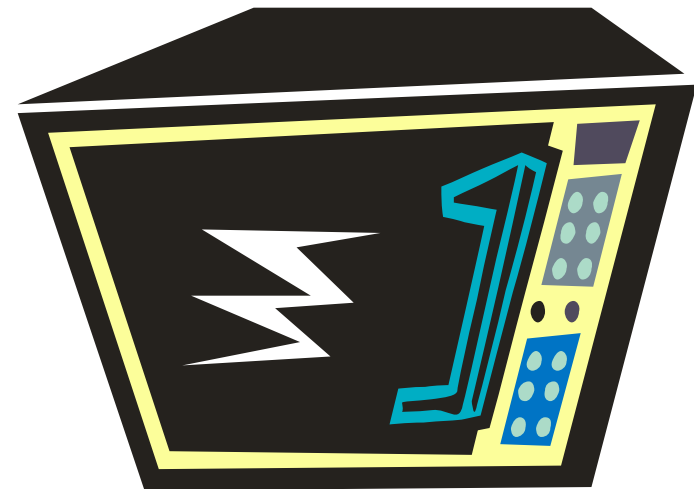
- Design for safety
- Verification, Validation & Test
- Change management
- Software Risk Analysis

◆ Risk traceability matrix

- FMEA-like table

◆ Certification components:

- Electrical safety reviews + tests
- Environmental stress tests
- Software review – source code & some process documents



Quality

1994 Pentium FDIIV bug:

- “We’ll replace the chip if you can prove the problem affects you”
- Eventually replaced chip for everyone who asked at cost of ~\$500M

Hardware Correctness

◆ Hardware testing is more manufacturing-centric

- Scan approaches
 - Scan paths to test flip-flops
 - Boundary scan to test chip-to-chip interconnects
- Automatic test generation

◆ But, what if the design is incorrect?

- The Pentium FDIV bug was a rude awakening
 - Math error in floating point division that affected only a few input values
 - Poor public relations resulted in demand for replacement chips → cost ~\$500M
 - But almost every CPU has bugs in it somewhere!
- Isolate subsystems and test in isolation
- Incorrect hardware design in many ways “feels” like a software problem...
- And, in Jan 2011 ... Intel found a bug with the Cougar Point support chip
 - Estimated \$700M total cost

Software Correctness

◆ This is a big can of worms

- In general, we can't prove software is correct (i.e., exactly meets the spec.)
- Even if we can prove it's correct, we don't know if the specification is correct
- So what we do is also include process (lectures on that coming up)

◆ Software reliability – how many defects when it ships?

- Can be inferred by tracking bug detection rates (ship it when you stop finding bugs in testing)
- Can be improved by better process
- In general, current state of knowledge is:
 - “keep testing until it takes a long time to find the next defect, then ship”

◆ Software “field reliability” – does it fail in the field?

- Difficult problem; not a lot to say about this yet except that it is an issue
- Components to software field reliability
 - Exposing design defects due to randomly occurring unusual events
 - Failures due to “code rot” and “resource leaks”

Configuration Management

◆ Make sure that the hardware and software is actually the right stuff

- For example, compute a checksum or secure hash of the binary image
- Make sure before you ship that you are shipping the right software version
- Have a formal build process to make sure you ship a clean build

◆ How can this go wrong?

- Someone leaves debug code in the final build
 - Watchdog timer accidentally turned off from single-step debugging
 - Back door factory access code left in (security problem)
- Someone compiles with wrong version of libraries, source code, etc.
- A virus gets into the build system and infects the built image ...

◆ Applies to hardware as well

- Want to make sure you know version and source for critical system components



Airbus A-380 bolt with part tracking information.

Size: 2 cm x 1 cm [30]

What V&V Approaches Are We Using?

- ◆ For the course elevator project, list V&V techniques:

Challenge: Ultradependability

◆ Ultradependable systems “never” fail

- But if they never fail, how can you know what the failure rate really is?

◆ Can you test for ultradependability?

1. How many tests to check all possible behaviors for this function:

int32 MyProc(int32 A, int32 B, int32 C)

- (who remembers this from last lecture?)

2. How long do you have to test to verify MTBF of 10^{-9} /hr?

(This is a typical aircraft failure rate target)

- Need to test longer than 10^9 hours and even then you didn't test enough
- In fact, need to test between 3^* and 10^* MTBF to verify MTBF
 - $10^* 10^9$ hours = 1,141,000 years of testing

Ultradependability Approaches

◆ Good process and lots of V&V

- Use good design methodology to reduce design defect rate
- Use proven, “mature” components
 - But, be careful not to expose hidden limitations with new conditions
- Test a large number of systems for a long time
 - Need completely failure-free operation during testing – even one failure can be too many for ultradependability
 - There is NO SUCH THING as a one-time failure... there are just situations waiting to re-occur in a different context
- Use formal methods on tractable, high-risk pieces
- Use fault injection to assess resiliency to problems that do happen

◆ This is the approach taken by safety standards

And Now, The Problem Gets Harder

◆ Embedded Internet –

- Can someone hack into your car?
 - ...into your house?
 - ...into your digital wallet?
 - ...into your medication pump?
 - ...into your pacemaker?
 - ...into your train?

- Security is now becoming part of the validation/verification/certification picture
 - Static checkers are the first line of defense, but much more is required
 - Penetration testing helps, but much more is required.

Review

◆ The Big Problem

- We need to ensure systems will really work, and we're on a tight deadline
- BUT, there are proven techniques that can help!

◆ Approaches:

- Design reviews to ensure designs are good before implementation
- Verification: making sure each design step does what it was supposed to do
- Validation: making sure the end result satisfies requirements
- Certification: a written guarantee that a system is acceptable for operational use

◆ In most embedded system companies, testing is the only real V&V

- BUT, testing isn't good enough for high-dependability / safe systems!
- Need as many V&V techniques as possible
- Ultimately, need a dependability case or safety case to be sure things are OK
- Later lectures will describe more rigorous processes for critical systems